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Status Final

**Geophysical Survey Nederwiek Wind Farm
Zone
Seabed Survey and 2D-UHRS survey.**

Annex 6 - Section IV

Scope of Work

Colophon

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Document Overview

Table 1: Document overview

Introduction
Aims
Site Description and Information Sources Survey Boundary
Planning Survey layout specifications
Acquisition, Processing, Interpretation Sections describing requirements for individual measurements: MBES SSS MAG SBP 2D-UHRS Seabed Sampling
Integration Sections describing the integrated output of multiple measurement sets Integrated Contact databases GIS Seismic Workstation Project
Reporting
Delivery

1 Introduction

1.1 Scope of this document

This document and its appendices detail the scope of the WORK as part of the CONTRACT that CLIENT has awarded to CONTRACTOR for carrying out geophysical investigations at Nederwiek Wind Farm Zone (NWWFZ), two optional buoy areas and an optional Demonstration Site (Site-X).

1.2 Background

The Ministry of Economic Affairs and Climate Policy is responsible for the legislative framework for the development of offshore wind farms in the Netherlands. Within this framework (a) (concession) tender(s) for permit for construction and operation of (a) wind farm(s) will be organized under the current regulation. As part of the tender documentation, the participants will receive an information package in which detailed information on the offshore site is included. Detailed information on the soil conditions at the site will be part of this information package.

Information on the soil conditions at the site is to be developed through a sequence of commissions for geological, geophysical, geotechnical and morphodynamical studies. Information will be presented as factual data, integrated and interpreted data (a Ground Model) and will be comprehensively reported.

One of the deliverables as a result of the geophysical survey campaign is a Preliminary Ground Model (PGM) of the areas. The contents of such a PGM are described in more detail in 1.6.

The Geophysical Survey follows and receives information from the Geological, Archaeological and UXO Desk Studies, and it is expected to precede and supply information to a geotechnical investigation, an Integrated Ground Model (IGM, integrating the results of Geological, Geophysical and Geotechnical investigations) and a morphodynamical investigation. The Integrated Ground Model is to be of sufficient precision to allow Offshore wind farm developers who want to participate in upcoming tenders in the Netherlands to make initial plans and costings for foundation design and cable installation.

This assignment is concerned with the geophysical investigation component, contributing to the information package to be provided to participants.

1.3 Site description

The NWWFZ is split into two Wind Farm Areas, a north area called Nederwiek noord (NW noord) and a south area called Nederwiek zuid (NW zuid), divided by a (planned) shipping lane, which have been investigated for the offshore wind development of the Netherlands. Nederwiek WFZ is part of the roadmap 2030+ as presented in Figure 1. NWWFZ is planned for a total capacity of 6 GW.

The NWWFZ is indicated in Figure 1, taken from Annex [6] section VII of the Tender information pack, Starting Points and Assumptions (SPA), and Figure 2 illustrating the Investigation Areas (IA) area specific to the Geophysical Surveys of Nederwiek.

A Geological Desk Study (GDS) to be provided by RVO for the NWWFZ provides information on the expected stratigraphic units, geological structures and possible influence on the design and the construction of offshore wind farms in the IA. The GDS will be available February 2023.



Figure 1. Newly announced Dutch Offshore Wind Farm Zones (Roadmap 2030+)

1.4 Two tenders for Geophysical Survey Campaigns

The Contracting Authority has chosen to split the planned geophysical survey campaign for the NWWFZ into two Tenders.

Tender for a Seabed Survey (SS) and 2D-UHRS survey (this tender), focusses on a seabed survey for NW zuid and a seabed survey for NW noord, including 2D-UHRS and SBP.

Tender for 3D-UHRS survey (separate tender - WOZ2220046), focusses on a full coverage 3D-UHRS survey for a 3D Investigation Area (IA) in NW zuid, including MBES and SBP, and additionally a 3D-UHRS and MBES survey of a corridor within NW noord.

With two tenders, the Contracting Authority aims to provide an opportunity for various contractors to bid for the two tenders, or both tenders, taking into account the overall planning of soil investigations in relation to the Routemap 2030+ Offshore Wind development planning.

1.5 Investigation Areas

It is the intention to obtain a single set of geophysical data, reports and drawings for each investigation area. For NWWFZ the IAs cover the area to be occupied by the Wind Farm Sites (WFS), including an additional buffer zone (500 m) around the WFS. However, the additional (500 m) buffer zone will not extend across the UK-NL maritime border for both NW noord and NW zuid.

The IAs for this tender are shown in Figure 2, and the vertices are provided in Table 2. In addition, optional IAs (two buoy areas, Site-X) are part of this scope and further described in section 1.5.1. The priority line plan for NW zuid is shown in Figure 3.

The coordinate points defining the IAs are provided in Table 2 in this document. Note that Table 2 represents the IAs to be surveyed to specification by the geophysical surveys and includes a buffer around the Wind Farm Sites.

General information on the Wind Farm Sites is provided in Annex [6] - section VII: Starting Points and Assumptions.

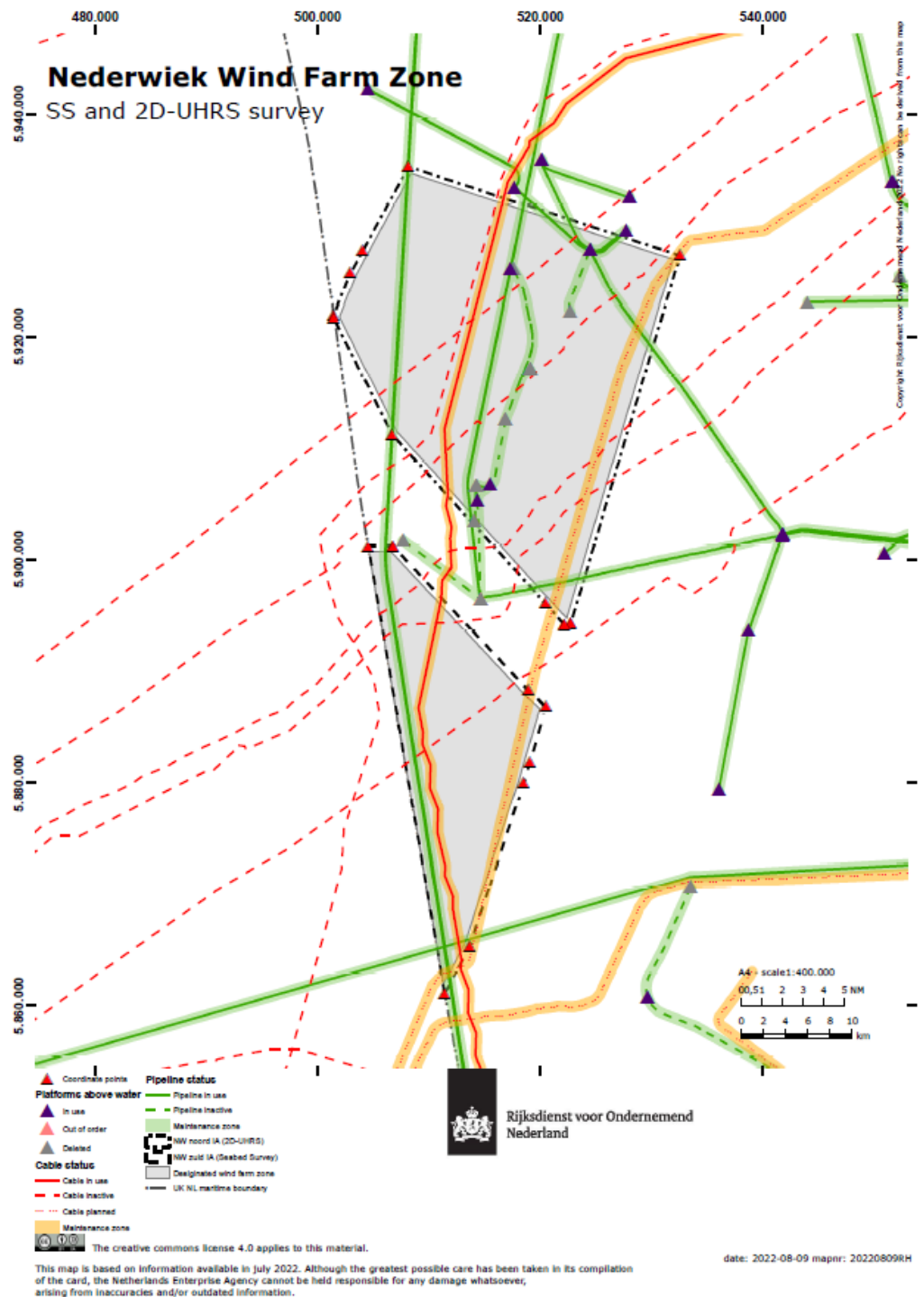


Figure 2. IAs to be surveyed during the geophysical campaigns at the NWWFZ.
Please note that the 3D UHRS seismic survey will be tendered separately.

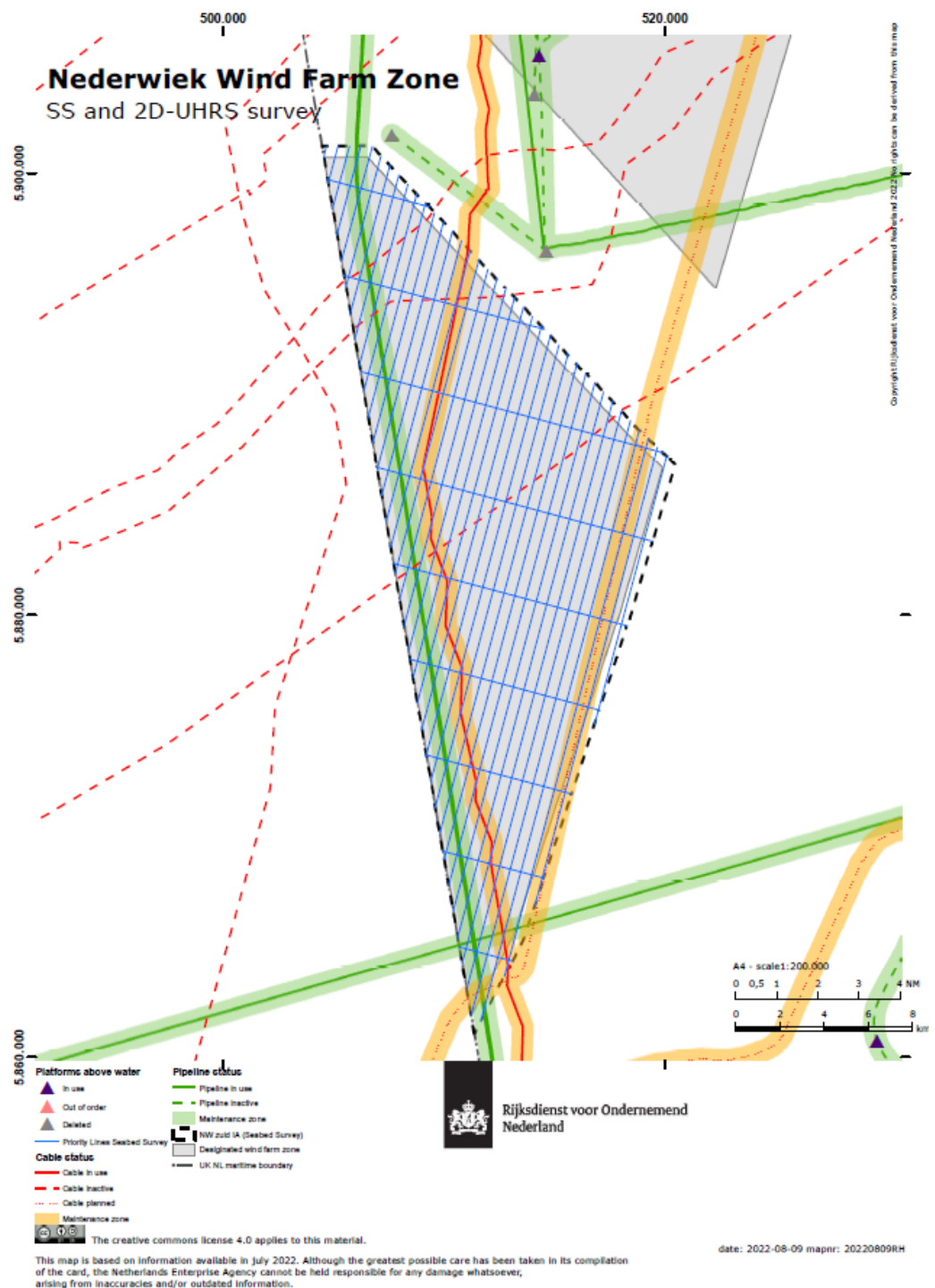


Figure 3. Geophysical survey plan showing the priority line plan throughout NW Zuid. Please note that the 3D UHRS seismic survey will be tendered separately.

Table 2. Coordinates of the vertices of the outer boundary of the Investigation Areas for the Geophysical Surveys for Nederwiek WFZ

Investigation Areas		
Nederwiek zuid IA for SS (incl. 500 m buffer zone)		
Point No.	Easting	Northing
IA_01	511369,8	5861040,2
IA_02	504466,2	5901194,0
IA_03	506725,4	5901232,5
IA_04	518871,8	5888344,5
IA_05	520477,7	5886811,5
IA_06	519003,6	5881829,6
IA_07	518455,0	5879975,8
IA_08	513597,6	5865294,5
Nederwiek noord IA for 2D-UHRS (incl. 500 m buffer zone)		
Point No.	Easting	Northing
IA_09	522141,3	5894225,4
IA_10	520439,5	5896087,9
IA_11	506622,8	5911208,8
IA_12	501409,3	5921687,1
IA_13	501379,2	5921898,3
IA_14	502898,6	5925735,6
IA_15	503966,3	5927701,1
IA_16	508096,3	5935303,9
IA_17	532515,8	5927346,3
IA_18	522709,8	5894356,0
Coordinate system: ETRS_1989_UTM_Zone_31N		
WKID: 25831 Authority EPSG		

1.5.1 *Optional Investigation Areas*

Metocean buoys

Two additional surveys for future installations of metocean buoys can be requested by CLIENT and shall be offered by CONTRACTOR with a price per km². The geographic locations of these optional buoy areas are not identified at time of publication of this tender. The IA for each buoy area is 3.75 km², with dimensions of 2.5 km x 1.5 km.

Site-X

An additional geophysical survey for another WFS can be requested by CLIENT and shall be offered by CONTRACTOR with a price per km². The final geographic location for this optional Demonstration Site (Site-X) is not identified at time of publication of this tender. Site-X has a planned size of 80 km², and is likely to be a rectangular in shape, approximately 8 km x 10 km. CONTRACTOR should offer pricing based upon the assumed rectangular shape and provided dimensions.

1.5.2 *Coordinate reference system and datum, and project coordinates*

The project coordinate reference system, horizontal datum and vertical datum are defined in Annex [6] - section VII: Starting Points and Assumptions. The coordinate points defining the IA are provided in Table 1 in this document. Note that Table 1 represents the IA to be surveyed to specification by the geophysical survey and includes a buffer around the Wind Farm Areas.

Vertical datums for this project are Lowest Astronomical Tide (LAT) (primary, default) and mean Sea Level (MSL) (secondary). More detail is provided in section 2.4.5.

1.6 **Aims of the geophysical surveys**

The aim of the geophysical soil investigations is to contribute to the bathymetrical, morphological and geological understanding of Nederwiek. The investigation is required to obtain seabed and sub-seabed information. The information is required to be suitable for the planning and preparation of geotechnical investigations, and suitable for integration into a ground model of sufficient quality to progress the design and installation requirements for offshore wind farms, including, but not limited to, foundations and cables.

The investigation is expected to provide:

- An accurate bathymetric dataset
- Information describing all seabed features of significance to the construction of wind farm facilities including but not limited to:
 - Sea floor sediments, their variation and morphology
 - any natural features such as boulders, scour hollows, pock-marks;
 - any non-natural features such as wrecks and debris (both known and previously unmapped), pipelines, cables, trawlmarks and infrastructure;
- Sub-Seabed datasets of sufficient penetration and quality to support construction of a ground model to at least 100 m below seabed, with resolution and signal-to-noise ratio optimised for production of an Integrated Ground Model
- A Preliminary Ground Model (PGM) of the site, including as a minimum;
 - Estimated elevation and depth below LAT of the base of mobile sediments if detectable.
 - Estimated elevation (depth in meters below LAT) and depth below seabed for a set of interfaces between principal geological formations or other horizons of interest;

- The locations of structural features or geohazards within the shallow geological succession including but not limited to faulting, accumulations of shallow gas, organic sediments/peat, buried/infilled channels, depth to hard ground/bedrock, soft sediments, structures associated with sub-glacial processes or glaciotectonism;
- Correlation with existing geophysical and geotechnical interpretation as available.
- The current position of existing (in service & out of service) cables and pipelines.
- A comprehensive interpretative report on the survey results obtained, describing the PGM; and
- A preliminary zonation of the site for input into the specification and scope for a geotechnical sampling and testing programme to follow the completion of the geophysical survey.

The output of the investigation shall be delivered in formats defined in this scope of work including digital data, Seismic Workstation and Geographic Information System project filesystems, chart data and reports.

It is expected that the IGM (to be developed under a separate, later commission following geotechnical data acquisition) will be a revision and significant enhancement of the PGM. It is expected to include refinement to data processing of sub-seabed data, ground-truth calibration of geophysically estimated depths, rationalisation of geotechnical and geophysical observations, refinement of the preliminary litho-stratigraphic model to include geotechnically relevant structures and the development of a 3D distribution of geotechnical parameters.

1.7 Execution of the investigation

CONTRACTOR shall take into account that arrangements on the survey plans (timing and location at the site where the survey is carried out) shall be made with other contractors working at the site and/or third parties using the space if required. It is expected that simultaneous operations (SIMOPS) might occur within the both the NW noord and NW zuid IA.

CONTRACTOR shall take into account arrangements for permits to use the survey equipment within the investigation area and shall adhere to requirements of environmental and other permits acquired by RVO.

CONTRACTOR shall take into account the close vicinity of the IAs to the UK/NL maritime boundary.

CONTRACTOR shall recognise that data acquisition will begin with a number of priority lines to be sailed within NW zuid. These lines will be required in order to provide clearance for a number of (sample) locations within a geotechnical survey (under separate tender). The requirement for the priority lines is that the processed data for the MBES, MAG, and SSS in NW zuid is delivered, to the specifications for these datasets as described in Section 2.4, at the earliest possible opportunity.

Forty-seven (47) priority lines within the Nederwiek zuid survey area will be acquired. In the main line direction, thirty-eight (38) lines will be acquired at a 500 m line spacing, oriented 015°–195° (parallel with the current). In addition, nine (9) crosslines will be acquired within the priority line plan, at a 4000 m line spacing, oriented 105°–285° (perpendicular to the mainlines). The total length of the priority lines is 670.6 km. The priority lines should be part of the main line plan. The priority line plan is provided within Figure 3, and additionally as a shapefile in the SPA annex.

Reduced lengths of thirty-seven (37) of the above described priority lines will also be acquired as priority lines within the tender for the 3D-UHRS survey, therefore

acquisition of the priority lines across these two surveys will need to be aligned. The reason for a different number of lines is that the two tenders will be operating within slightly different survey areas. This means an element of co-creation between the two tenders (seabed survey and 2D-UHRS survey tender, and 3D-UHRS survey tender – see section 1.4) is required, and potentially some CONTRACTOR flexibility with line planning on both tenders.

The requirement is to survey, process, and deliver the data for the priority lines in NW zuid at the latest by 15/4/2023.

Delivery of the final report for NW zuid is preferred by 15th September, 2023, and required by 31th October, 2023. Delivery of the final report for NW noord is preferred by 15th January, 2024, and required by 1st March, 2024.

1.8 Co-creation

The CLIENT wishes to work with and encourages the concept of co-creation in the project. This means that new working forms between CONTRACTOR and CLIENT will be explored. In this context, the following co-creation opportunities are foreseen:

- Work together as a team between RVO, RVO experts and CONTRACTOR to come to the optimum result for all parties involved;
- Acquisition of priority lines geophysical data to support and provide clearance for a geotechnical campaign;
- Development of the Preliminary Ground Model;
- Dissemination activities such as webinar and answering questions from the market.
- Reduction of environmental impact for survey operations.

1.9 Timing of the investigations

- The geophysical survey for NW zuid is expected to be carried out from Q1 2023, beginning with the priority lines.
- Seabed Information (MBES, SSS, MAG) of priority lines at NW zuid for the preparation of a geotechnical borehole campaign, are to be processed and delivered in advance of the Geotech campaign for NW zuid (therefore processed priority line data should be delivered at the latest by 15th April 2023). The priority line plan is shown in Figure 3, and included as a shapefile within the SPA annex.
- The 2D-UHRS geophysical survey for NW noord can be started in Q1 2023, and is expected to end in September/Okttober 2023.
- CONTRACTOR can offer a one or two vessel solution taking into account the intended start and end times of the survey.
- The timing of the execution of the geophysical survey for the optional buoy areas, and optional Site-X, will be after the geophysical survey of NW noord.

1.10 Available information

1.10.1 WFZ specific information

CLIENT will carry out desk studies on NWWFZ. The following desk studies will become available on <https://offshorewind.rvo.nl>

- Geological desk study; (expected publication date: February 2023)
- Archaeological desk study; (expected publication date: February 2023)
- UXO desk study; (expected publication date: January 2023)

The CLIENT will endeavour to give results of these studies earlier to the winning CONTRACTOR.

1.10.2 *Other information*

Further, for information, the results of the geophysical and geotechnical surveys carried out for Borssele, HKZ, HKN, HKW, TNW and IJV WFZ are available at <https://offshorewind.rvo.nl/>. It should be noted that this scope of work deviates from those of previous investigations *and may introduce additional requirements*.

2 Scope of Work

2.1 Survey requirements per investigation area

This scope of work covers multiple geographic locations with different survey requirements per IA listed in Table 3.

Table 3. Geophysical survey requirements per IA

	Buoy areas	Nederwiek noord	Nederwiek zuid	Area X
MBES	X	X	X	X
SSS	X	X	X	X
MAG	X	X	X	X
SBP	X	X		X
2D UHRS	X	X		X
Grab samples		X	X	X

2.2 General scope of work

2.2.1 Activities

The activities which are to be carried out to obtain the information detailed in section 1.6 are the following:

- **Preparation:**
 - all preparatory works required for the geophysical surveys, including preparation of all plans that need to be provided (and approved) before the works can start.
 - Permit to perform survey works with the proposed equipment within the IA.
- **Data Acquisition and processing:**
 - High resolution bathymetric and backscatter survey
 - High resolution side scan sonar survey
 - Magnetometer survey
 - Shallow Penetration Sub-Bottom Profiler (SBP) survey
 - 2D Multi-Channel Ultra High-Resolution Seismic (2D-UHRS) profiling survey
 - Seabed Sampling (Van veen grab sampler, or similar)
- **Data Interpretation:**
 - Produce derived interpretation products including; contact lists of seabed features and sediment boundaries based on MBES and SSS data, and lists of MAG contacts (for Buoy areas, NW noord, NW zuid, and Area X). And additionally, interpreted horizons observed in SBP and 2D UHRS data within the Buoy areas, NW noord, and Area X, and resultant gridded surfaces.
 - Integrate the survey elements into a Preliminary Ground Model (for areas with 2D UHRS)
- **Quality Assurance and Quality Checking**
 - Apply a coherent Quality Management Plan throughout the work
- **Reporting:**

- Create final data package with QA and metadata elements
- present the results in clear reports and drawings, detailed in 2.7.3
- Provide zonation and extents of sub-seabed geological units as guidance for design of a geotechnical investigation campaign
- Provide input for a morphodynamical study.
- Provide input for an archaeological study.
- **Delivery**
 - Products of the survey are to be delivered as a coherent and integrated data package with clear documentation.

This scope of work is designed to provide a minimum acceptable specification and contains important requirements throughout the document. Key requirements for survey layout are provided in sections 1.3 and 2.3.2, and for resolution of positioning and individual measurements in section 2.4.

The description of the survey aims, should inform the CONTRACTOR in preparing their proposal which should clearly describe their suggested specification suitable to achieve the survey aims.

It should be recognised that the results of the survey are to be integrated with other products and made available to multiple parties as part of the information package associated with the tender process described in section 1.1. The deliverable products of the survey must allow third parties receiving the data package to evaluate, reprocess, reinterpret or otherwise rework the data to fit the needs of their processes. To this end, it is emphasised that raw data, positioning information, reporting and metadata are important elements of the deliverable package.

2.2.2 *Deliverables*

The survey data together represent a significant array of elements which are required to be arranged in a coherent format. The specifications of raw, processed, and interpreted deliverables from individual survey elements are described within their respective sections.

Three integrated deliverables are required: a GIS project (*ESRI ArcGIS is preferred*) containing *all* processed and integrated elements that may be represented in GIS; a single seismic workstation project (*IHS Kingdom is required*) containing *all* the subsurface data elements, and an integrated interpretative report describing the PGM.

The contents of these integrated deliverables are to be supplemented by raw data suitable to allow reprocessing, intermediate processed data as specified for each data element, final data, interpreted data, metadata and reporting.

2.3 **Preparation**

2.3.1 *Scrutiny of available information*

CONTRACTOR shall scrutinise the information that has been made available by CLIENT as specified in 1.9. Information that is relevant for carrying out the WORK shall be considered while preparing the WORK.

2.3.2 *Design Requirements of the Survey Layout and Configuration*

It is anticipated that the acquisition of geophysical, hydrographic and environmental datasets may involve one or more passes across the IA. The CONTRACTOR shall select their optimum survey layout and acquisition configuration (e.g. single or multiple passes, single- or multi-vessel solution) to achieve the survey objectives and data quality requirements.

CONTRACTOR is required to determine an effective logistical solution with regards to the requirements of each measurement type within the IA boundary as indicated in section 1.4.

The following criteria represent layout requirements for the proposal, covering the entire IAs where applicable according to section 1.5:

2.3.2.1 Nederwiek noord

- Multi-Beam Echo Sounder (MBES) bathymetry and backscatter, Side-Scan Sonar (SSS), magnetometry (MAG), shallow penetration, high resolution Sub Bottom Profiler (SBP¹) and 2D Multi-Channel Ultra High Resolution Seismic (2D-UHRS) are to be acquired with isotropic parallel primary lines at not greater than 70 m line spacing. A line spacing should be chosen by the CONTRACTOR to achieve the required data quality and sufficient coverage on all sensors without relying on infill. The vessel shall be steered so that the CMP is positioned on the intended line track.
- The primary line orientation for 2D data shall be oriented at CONTRACTOR's discretion taking into account technical and quality considerations for all sensors, survey efficiency, representative tidal current speed and direction, and interfaces at the survey boundaries.
- Secondary lines (tie or cross lines) are to be within 10° of the orthogonal to the primary lines.
- Secondary lines are to be acquired at a maximum spacing of 420 m for the MBES, SSS, MAG, SBP and 2D-UHRS surveys
- The maximum separation of the 2D-UHRS near-channel mid-point track and the SBP track on all lines is required to be 15 m.
- Minimum length of any line or line segment shall be 500 m.
- Every line or line segment shall have at least two intersections, with intersections within 420 m of each line end
- At least 20 grab samples (Van Veen grab or similar) distributed to representatively sample the seabed sediments across the site for seabed soil classification.
- Two line segments within the IA, individually up to 30 km length (totalling a maximum of 60 km length) are to be re-surveyed up to three times over the survey duration to record bathymetry data, providing information on seabed mobility analysis. These repeated lines should be factored within the regular survey lineplan and not priced as additional tie-lines.
- A dual magnetometer system (transverse gradiometer) is preferable over a single magnetometer system, and use of a separate tow point is preferred rather than being piggy-backed from the SSS (as specified in Section 2.4.8).

2.3.2.2 Nederwiek zuid

- Multi-Beam Echo Sounder (MBES) bathymetry and backscatter, Side-Scan Sonar (SSS), magnetometry (MAG).
- The primary line orientation for shall be oriented at CONTRACTOR's discretion taking into account technical and quality considerations for all sensors, survey efficiency, representative tidal current speed and direction, and interfaces at the survey boundaries. (The preferred orientation for the primary lines is parallel to the priority lines)
- A line spacing should be chosen by the CONTRACTOR to achieve the required data quality and sufficient coverage on all sensors without relying on infill taking all specifications of the sensors in this document into account.

¹ Sub Bottom Profiler (SBP) refers in this document to systems with shallow penetration i.e. Pinger, Chirp or parametric or equivalent systems

- Secondary lines (tie or cross lines) are to be within 10° of the orthogonal to the primary lines.
- Secondary lines are to be acquired at a maximum spacing of 1000 m for the MBES, SSS, MAG.
- Minimum length of any line or line segment shall be 500 m.
- At least 16 Grab samples (Van Veen grab or similar) for seabed soil classification.
- Two line segments within the IA totalling a maximum of 20km are to be re-surveyed up to three times over the survey duration to record bathymetry data, providing information on seabed mobility analysis. These repeated lines should be factored within the regular survey lineplan and not priced as additional tie-lines.
- A dual magnetometer system (transverse gradiometer) is preferable over a single magnetometer system, and use of a separate tow point is preferred rather than being piggy-backed from the SSS (as specified in Section 2.4.8).

2.3.2.3 Buoy areas (optional scope)

- Multi-Beam Echo Sounder (MBES) bathymetry and backscatter, Side-Scan Sonar (SSS), magnetometry (MAG), shallow penetration, high resolution Sub Bottom Profiler (SBP¹) and 2D Multi-Channel Ultra High Resolution Seismic (2D-UHRS) are to be acquired with isotropic parallel primary lines at not greater than 70 m line spacing. The vessel shall be steered so that the CMP is positioned on the intended line track.
- The primary line orientation for 2D data shall be oriented at CONTRACTOR's discretion taking into account technical and quality considerations for all sensors, survey efficiency, representative tidal current speed and direction, and interfaces at the survey boundaries.
- The maximum separation of the 2D-UHRS near-channel mid-point track and the SBP track on all lines is anticipated to be 15 m.
- A dual magnetometer system (transverse gradiometer) is preferable over a single magnetometer system, and use of a separate tow point is preferred rather than being piggy-backed from the SSS (as specified in Section 2.4.8).

2.3.2.4 Site-X (optional)

- Multi-Beam Echo Sounder (MBES) bathymetry, Side-Scan Sonar (SSS), magnetometry (MAG), shallow penetration, high resolution Sub Bottom Profiler (SBP²) and 2D Multi-Channel Ultra High Resolution Seismic (2D-UHRS) are to be acquired with isotropic parallel primary lines at not greater than 70 m line spacing. The vessel shall be steered so that the CMP is positioned on the intended line track.
- The primary line orientation for 2D data shall be oriented at CONTRACTOR's discretion taking into account technical and quality considerations for all sensors, survey efficiency, representative tidal current speed and direction, and interfaces at the survey boundaries.
- Secondary lines (tie or cross lines) are to be within 10° of the orthogonal to the primary lines.
- Secondary lines are to be acquired at a maximum spacing of 420 m for the MBES, SSS, MAG, SBP and 2D-UHRS surveys
- The maximum separation of the 2D-UHRS near-channel mid-point track and the SBP track on all lines is anticipated to be 15 m.

² Sub Bottom Profiler (SBP) refers in this document to systems with shallow penetration i.e. Pinger, Chirp or parametric or equivalent systems

- Minimum length of any line or line segment shall be 500 m.
- Every line or line segment shall have at least two intersections, with intersections within 420 m of each line end
- At least 8 grab samples (Van Veen grab or similar) distributed to representatively sample the seabed sediments across the site for seabed soil classification.
- Two line segments totalling a maximum of 20 km are to be re-surveyed up to three times over the survey duration to record bathymetry data, providing information on seabed mobility analysis. These repeated lines should be factored within the regular survey lineplan and not priced as additional tie-lines.
- For associated transit rates related to Optional Site-X, see Annex 4.
- A dual magnetometer system (transverse gradiometer) is preferable over a single magnetometer system, and use of a separate tow point is preferred rather than being piggy-backed from the SSS (as specified in Section 2.4.8).

2.3.2.5 Additional line km outside IA

- An optional 50 line km's are to be surveyed outside of NWWFZ with regards to nearby investigation areas with MBES, SBP and 2D-UHRS systems active. These lines are outside of the regular line plan, and are separate to the repeated morphological study lines. The exact locations of the tie lines are to be determined after contract award.

2.3.2.6 Multiple vessels

Up to two (2) vessel(s) may be used by the CONTRACTOR to acquire the required datasets (MBES/SSS/MAG/SBP/2D-UHRS/sampling). Acceptable solutions include but are not limited to the use of the following configurations:

- One- or two-vessel solution each with a single pass to cover the MBES/SSS/MAG/SBP/2D-UHRS/sampling surveys concurrently.
- One- or two-vessel solution with multiple passes to cover the MBES/SSS/MAG/SBP/2D-UHRS/sampling surveys consecutively.

It is required that MBES data are acquired, processed and delivered with the 2D-UHRS survey to support source and receiver height compensation in UHRS (re)processing.

Two pass or two vessel operations must deliver the results as a single, coherent body of data. All data must be referenced to a common vertical datum. Final time-domain seismic data must be corrected to a time-pseudo-datum corresponding to the vertical datum(s), all non-dipping water bottom reflections must tie within ≤ 0.2 ms. Vessel specification sheets including instrumentation and towing diagram, settings and appropriate procedures are required to be produced, maintained and followed where multiple vessels and/or multiple personnel rosters contribute to the same measurement type.

Equipment interference must be minimised in all cases, shall be proactively monitored and reported, and shall not impact the data quality. The mitigation measures for potential sources of interference should be described in the proposal.

2.3.3 *Permits and notifications*

CONTRACTOR shall obtain and manage all necessary permissions other than the environmental exemption (underwater noise), and/or notifications, to perform the survey (including all permissions and fees necessary for access and safety arrangements to harbours and offshore positions). CLIENT shall arrange for environmental exemption, on the basis of the documentation provided by the tenderers, and CONTRACTOR shall work within the requirements of this permit throughout survey activity.

Operation of an Acoustic Deterrent Device (ADD) "Pinger" during all offshore works is mandatory to CONTRACTOR. Specifications of the active sources for sub-bottom profiler devices (all sources for SBP, 2D-UHRS) shall not vary during the project from those supplied to the CLIENT for application of the ecological exemption (underwater noise). Furthermore, a soft start procedure for the sub bottom profiler devices should be in place before the start of the survey works.

NW zuid and NW noord will be split by a planned shipping lane (corridor separating on Figure 2). CONTRACTOR should be aware of planned activities in the area.

2.3.4 *UXO assessment and measures*

The general risk regarding the presence of UXO (unexploded ordnance) will be assessed and reported in a separate desk study. The report will be published in January 2023. Draft results of the UXO desk study can be shared in 2022.

CONTRACTOR shall carry out an independent UXO risk assessment for the proposed seabed grab sampling locations in NW noord, NW zuid (and optionally Site X), and undertake any required additional measures in order to reduce the risk to as low as reasonably practical (ALARP). The approach shall be described in the Project Implementation Plan.

2.3.5 *Project Plans*

CONTRACTOR shall prepare all required project plans as required by the CONTRACT. These documents (the Project Documentation) shall include planning for the execution of operations, quality management and safety management. The organisation of these elements shall be according to the CONTRACTOR's normal working practice but the planning material must include (but not be limited to) the following for every data type to be acquired:

- Project implementation plan including method statements and safe systems of work
- Quality monitors
- Mobilisation, equipment verification, parameter optimisation
- Data acceptance criteria per sensor
- Spares inventory management
- If project plan is divided in multiple documents, a mapping document is required to provide an overview and latest versions for each document.

And for the general project management:

- Safety management and emergency response
- Quality management throughout the project
- Plans to interface between CONTRACTOR's offshore team, CONTRACTOR's onshore management, CLIENT's offshore representative and CLIENT's onshore team
- Interface between the project and any third parties requiring it

CONTRACTOR shall only commence the WORK when all project plans have been reviewed by CLIENT and all comments made by the CLIENT are resolved and approved.

For all revisions a document version with track changes on, a document review form (DRF) and a final version are expected to be provided for ease of reviewing changes.

Generic descriptions in the project plan which will be updated upon /after award of the contract shall be highlighted and provided with (explicit) time bound plan providing insight when generic information will be replaced. Project specific information will be of added value.

The preparation of Project Documentation is expected to include an onshore based Technical Kick-Off Meeting (TKOM) and Hazard Identification and Risk Assessment (HIRA, refer to Annex [6] - section V HSE Requirements) as physical meetings prior to a Vessel Kick-Off Meeting (VKOM) to be held as mobilisation starts.

The TKOM shall at least address following topics (with the final agenda being agreed between CLIENT and CONTRACTOR before the TKOM):

- Project Implementation Plan
- Project schedule/planning
- Initial sensor/survey configuration
- Line plan (incl. priority line plan NW zuid)
- Offshore data QC
- Data acceptance criteria per sensor
- Offshore testing phase/survey parameter optimisation
- Mobilisation acceptance

Offshore equipment verification and parameter testing shall be required input for finalised production procedures, to be completed after the offshore testing phase.

2.4 Data acquisition

2.4.1 Mobilisation and demobilisation

Mobilisation of the vessel(s) to the site will be considered completed when all necessary survey and project documentation, equipment, spares and personnel are accepted as operational and optimised to the specification agreed by the CLIENT and approved by the CLIENT. Following equipment verification (including spares) an offshore testing phase shall be conducted to an agreed plan to demonstrate sensor settings are optimised to meet the survey requirements set out in this SoW. All required verifications, optimisations and calibrations of vessel and equipment (defined during TKOM) need to be documented, agreed, and signed off by both the RVO onshore QES, and onboard CR (this is regarded as part of the mobilisation).

Where the final configuration of any survey equipment is not pre-defined in plans, (*e.g. where on-site configuration or optimisation is required*) ALL deployed options and spares are to be verified as operational during the mobilisation phase.

The harbour to be used for mobilisation of survey vessel(s), equipment and personnel is chosen by the CONTRACTOR with approval of the CLIENT.

Demobilisation of the vessel will be authorised when all the data required have been acquired and have passed field QA/QC criteria to the satisfaction of the CLIENT's offshore representative.

2.4.2 Testing

Following equipment verification, a testing phase shall be implemented to establish the appropriate configuration and parameterisation of data acquisition equipment and finalisation of the survey QA parameters. Where data processing operations are critical to either in-field QA/QC or evaluation of the suitability of the data acquisition configuration, design and parameterisation of these operations shall be part of the testing phase. A testing programme shall be agreed as part of the planning phase, and should include the collection of data properly representative of the range of ground conditions at the site.

Provision shall be made for tests to be evaluated, agreed, and signed off by both the RVO onshore QES, and onboard CR.

Acceptance by CLIENT of data acquisition configuration is expected to take place as soon as possible after mobilisation and testing. Production data acquired prior to

acceptance of the data acquisition configuration is acquired at the CONTRACTOR'S risk.

Up to two (2) CLIENT representatives may be deployed offshore on each vessel during testing to facilitate optimisation and approval – suitable accommodation and messing shall be provided. If a port call is required to allow disembarkation of the CR, this shall be arranged to coincide with a planned port call at no charge, or a rate for a port call with no other purpose for CONTRACTOR specified in the proposal.

A draft mobilisation report (including calibration, verification, and testing phase results) is to be provided within two calendar weeks of acceptance of the data acquisition configuration. This report is to be included as an appendix to the Operations Report.

Examples of tests to conduct during testing phase (complete list shall be agreed on during TKOM):

- Seismic source – test source energy level, polarity, and frequency content.
- MBES – test multiple pulse width and gain settings for backscatter (if applicable).
- SSS – resolve subtle details on outer swath in HF channel. Carry out a verification exercise to demonstrate positioning accuracy.
- SBP – test multiple pulse width and types, frequency selection.
- Navigation – test correct navigation string is applied to each sensor, check measured layback where relevant.
- General – describe the timing/firing sequence, and steps taken to maximise lateral resolution and avoid interference between sensors.

2.4.3 *Lost Equipment*

CONTRACTOR shall be responsible at his own cost for marking the location of, and recovery of, equipment dropped or lost during the execution of the project. CONTRACTOR shall mark the positions of equipment on or below the seabed with marker buoys if necessary and recover the equipment at the earliest possible opportunity. All equipment shall be removed to a reference level which is the trough of mobile sand waves in the area.

All reasonable possible attempts should be made to recover lost equipment.

For any non-electronic lost equipment not being recovered a fee of 500€ per piece is due to be paid by CONTRACTOR to an NGO selected by CLIENT for the purpose to support marine environmental protection.

For any other lost equipment not being recovered with circuit boards, hazardous fluids or batteries inside, a fee of 5000€ per piece is due to be paid by CONTRACTOR to an NGO selected by CLIENT for the purpose to support marine environmental protection.

2.4.4 *Positioning*

Navigational accuracy, tidal height accuracy, frequency and method of navigation checks and positioning specifications shall be stated in project documentation. Navigation checks and positioning calibrations shall be completed prior to leaving harbour at mobilisation. The combined precision and accuracy of the navigational positioning capability and post-processing methods must be sufficient to allow horizontal positions of moving survey hardware to be determined to within ± 1 m, with height values within ± 0.1 m. Static measurements shall have DGPS positioning to ± 0.1 m in all 3 dimensions. Equipment must be positioned using DGPS (or better) for surface and DGPS (or better) and USBL for subsurface gear.

USBL system accuracy: ≤ 0.5 % of Slant Range

Accurate positioning is essential. Coverage requirements dictate the course of MBES and SSS data acquisition, while pre-plot line-plans are the primary target for positioning of MAG, SBP and UHRS data acquisition. Where seismic data are intended to be co-located an achievable positioning tolerance is to be agreed with the CLIENT, prior to the acquisition of production data. Co-location is defined as a common track of the reflection point at the seabed (near channel reflection point for UHRS).

The exact position of the measurements must be recorded with an acoustic tracking system such as a USBL, giving the position of the equipment underwater relative to the vessel surface position.

The acoustic underwater positioning system must be used to provide X, Y and Z offset to all seabed deployed systems. The offset to each sensor is used in real time to provide an absolute position coordinate and logged together with all raw data relative to a common DGPS time base.

The CONTRACTOR must calibrate or verify the system(s) in the work area or at similar water depth and demonstrate the validity of the calibration procedures prior to initiating survey work.

2.4.5 *High Resolution Bathymetric Survey*

The objective of the High-Resolution Bathymetry (HRB) Survey is to contribute to the model of the seabed including:

- seabed elevations / depths relative to LAT and MSL;
- identification and mapping of static and potentially mobile bedforms;
- identification and mapping of potential hazards to the development of offshore wind farm infrastructure at the site;
- identification and mapping of natural and anthropogenic seabed features and objects;
- classification and mapping of sea-bed sediments.

Required elements

The HRB Survey must include:

- Survey wide bathymetric measurement
- Repeat measurements on up to two transects, up to additional three passes
- Sound velocity measurement (real time at receiver and min. 2 daily vertical profiling)
- Backscatter strength measurement for input to AGDS analysis
- Water Column Data over wrecks

Specifications

Acquisition of high-resolution bathymetric data using a Multi-Beam Echo Sounder (MBES) with at least 100% coverage of the IA.

Data will be acquired to exceed IHO Standard S-44 Edition 6³ Special Order standard according to specifications issued by the International Hydrographic Association (IHO). The system shall be capable of providing a minimum of 6 soundings per 0.5x0.5 m cell when deployed on-site. The CONTRACTOR shall define the technology and line spacing employed to meet these requirements based on existing water depth information. Compliance with IHO Standard S-44 Edition 6 Special Order uncertainty thresholds must be demonstrated in the Field report.

³ https://iho.int/uploads/user/pubs/Drafts/S-44_Edition_6.0.0-Final.pdf

Matrix Code: Ba9, Bc10, Bd8, Be6, Bg9, Bh9 + 6 Pings/0.5x0.5m.

MBES data must be recorded with optimised (preferred are consistent) settings for backscatter and bathymetrical analyses of the seafloor. Guidance on best practice and optimised settings for backscatter surveys can be found in the GEOHAB backscatter report⁴.

Water column data shall be recorded when surveying over wrecks or similar seafloor hazards to allow a precise detection of vertical objects protruding the seafloor.

The bathymetry data forms a baseline for the anticipated morphodynamical study. To support this work, repeat occupation of up to two suitable line segments is required, at the beginning and end of the geophysical survey period and up to two additional passes, one to be saved for acquisition immediately following any significant storm event. The location of the line segments is to be confirmed at the TKOM.

Guidance

The system should incorporate a sound velocity probe to monitor the speed of sound in water in real time at the receiver to provide a constant comparison against a vertical Sound Velocity Profile (SVP) through the entire water column. The sound velocity probe incorporated into the MBES system should have an accuracy of better than ± 0.15 m/s.

Vertical SVPs to measure the speed of sound in water should be obtained in the survey area at a minimum of twice per day. It is recommended that SVPs are obtained at the start and end of each day, and initially at low and high tides. SVP acquisition intervals may be increased with the agreement of the CLIENT's OFFSHORE REPRESENTATIVE. Measurements should be made using a calibrated velocimeter or calculated using temperature and salinity measurements, to create a static vertical SVP. Measurements should be taken continuously between the sea surface and the seabed in a vertical profile.

Reported water depths from MBES must be sound velocity corrected and reduced to LAT by applying the latest LAT model for the Dutch North Sea (NLLAT18⁵). Bathymetry relative to MSL shall be derived *from* the LAT referenced data, for MSL reduction the latest DTU21⁶ Mean Sea Level model shall be used. The methods for reduction shall be comprehensively explained in detail in the project plan and the final report.

Backscatter/snippets data from seabed returns should be logged and processed for use in seabed characterisation using an AGDS together with side-scan sonar and sample data as appropriate. AGDS analysis should be carried out by an experienced AGDS analyst who is demonstrably familiar with the specific AGDS used. The methods for AGDS shall be comprehensively described in detail in the project plan and the final report.

Seabed sample acquisition is required during this survey campaign (section 2.3.7).

Data Processing

Data shall be reduced to datum, then gridded to produce a raster Digital Terrain Model (DTM) of the seabed at 0.5 x 0.5 m resolution or better. Grids at 1.0 x 1.0 m and 0.5 x 0.5 m are required.

⁴ Lurton, X.; Lamarche, G. (Eds) (2015) Backscatter measurements by seafloor-mapping sonars. Guidelines and Recommendations. 200p. <http://geohab.org/wp-content/uploads/2014/05/BSWGREPORT-MAY2015.pdf>

⁵ <https://english.defensie.nl/downloads/applications/2020/06/12/nllat2018>

⁶ <https://ftp.space.dtu.dk/pub/DTU21/> Please note that DTU is in the TOPEX and mean tide system for use with satellites. DTU21 needs to be updated to ETRS89 ellipsoid and Tide Free system for consistency.

The reduction method and vertical and horizontal datums used must be compliant with Section 2.4.5, 2.4.6 and IHO standards and guidance (IHO, 2005⁷; IHO, 2020⁸). Details of the vertical reduction process (MSL and LAT) must be included in the Operations Report and demonstrated to meet or exceed the requirements of the specified standards and guidelines, using appropriate illustrations.

Full QA/QC must be carried out in order to generate statistical proof that the survey meets the requirements. A statistical description of Total Horizontal Uncertainty (THU) and Total Vertical Uncertainty (TVU) must be generated with the resulting values being demonstrated to meet or exceed the 'Special Order' minimum requirements described in the IHO Standard S-44 Edition 6. A quantitative assessment of the feature detection thresholds for the survey must also be included and demonstrated to meet or exceed the Special Order minimum requirements.

Interpretation

MBES Contact picking should be carried out based on gridded data or point cloud data to support the interpretation of SSS Contacts.

MBES Contacts must be identified and should be listed separately in a spreadsheet, along with a description of the Contact length, width and depth/height where appropriate.

Contacts must be classified *at minimum* into the following categories:

- Wreck-associated, correlated to local wreck registers, if available, and associated magnetometer/SSS Contacts;
- Debris-associated, correlated to associated magnetometer/SSS Contacts;
- Possible pipeline (with appropriate ID to indicate where multiple Contacts are thought to be associated with the same pipeline);
- Possible cable (with appropriate ID to indicate where multiple Contacts are thought to be associated with the same cable);
- Mound;
- Depression.

Deliverables

The following deliverables including their metadata are required at minimum:

Table 2: MBES deliverables						
Item ID	Measurement	Module R = Raw P = Processing I = Interpretation	Description	Resolution	Format	Load into GIS-database
a1	MBES	R	MBES output files	n/a	Native data format	N
a2		P	Despiked, cleaned, positioning corrected soundings as x,y,z, per line, full density		Ascii+prj	N
a3			Despiked, cleaned, positioning corrected MBES backscatter data as x,y,z, per line, full density		Ascii+prj	N
a4			Subset of a2 for repeat lines		Ascii+prj	N

⁷ IHO. 2005. Manual on Hydrography (C-13). International Hydrographic Bureau, Monaco, 1st ed. (corrections to February 2011), 36 pp.

⁸ IHO. 2020. IHO Standards for hydrographic surveys (S-44). IHO Publications No. 44. International Hydrographic Bureau, Monaco, 6th ed., 49 pp

a5		Subset of a3 for repeat lines		Ascii+prj	N
a6		Speed of sound in seawater vertical dip data profiles	n/a	.xlsx, PDF, Ascii+prj	N
a7		MBES tracks (navigation) data, Survey line ID and fix point index	n/a	.gdb, Ascii+prj	Y
a8		Gridded bathymetry, relative to LAT	0.5 m	Ascii+prj	N
a9		Gridded bathymetry, relative to MSL	0.5 m	Ascii+prj	N
a10		Gridded bathymetry, relative to LAT	0.5 m	Geotiff	Y
a11		Gridded bathymetry, relative to MSL	0.5 m	Geotiff	Y
a12		Gridded bathymetry, relative to LAT	1.0 m	Ascii+prj	N
a13		Gridded bathymetry, relative to MSL	1.0 m	Ascii+prj	N
a14		Gridded bathymetry, relative to LAT	1.0 m	Geotiff	Y
a15		Gridded bathymetry, relative to MSL	1.0 m	Geotiff	Y
a16		Height adjusted gridded bathymetry relative to LAT	1.0 m	.gdb	Y
a17		Height adjusted gridded bathymetry relative to LAT	0.5 m	netCDF*	Y
a18		Tile map index [polygon]	n/a	.gdb	Y
a19		Total Vertical Uncertainty (TVU) gridded XYZ	0.5 m	Ascii+prj	N
a20		Total Horizontal Uncertainty (THU) gridded XYZ	0.5 m	Ascii+prj	N
a21		Total Vertical Uncertainty (TVU) raster	0.5 m	Geotiff	Y
a22		Total Horizontal Uncertainty (THU) raster	0.5 m	Geotiff	Y
a23		Bathymetric contours, typically 1 m interval.	n/a	.gdb	Y
a24		Backscatter data, gridded xyz	1.0 m	Ascii+prj	N
a25		Backscatter data, geo-referenced raster	1.0 m	Geotiff	Y
a26		Bathymetry slope in degrees, xyz	0.5 m	Ascii+prj	N
a27		Bathymetry slope in degrees Georeferenced raster	0.5 m	Geotiff	Y
a28		Water column data over wrecks and obstacles	n/a	native	N
a29		time-stamp indexed text file of tidal correction	1 minute	.txt	N
a30		MBES Contact list	n/a	.xlsx	N
a31	I	MBES Contact list [pnt]	n/a	.gdb	Y

Notes on MBES deliverables

Raw:

- Raw output files from the MBES instrument are required as native data format of the used sensor/hydrographic survey software

Processed:

- MBES backscatter data, in a standard format to be agreed.
- MBES trackplot (fix point and line).
- The bathymetry at a resolution of 0.5 x 0.5 m or better reduced to datums and produced by gridding the swath bathymetry data to a regular grid, as a single or tiled set of xyz text files (*.xyz/*.pts) without overlaps together with projection information saved in a .prj file; **and** a single or tiled raster/grid without overlaps.
- Bathymetry contours at an appropriate interval for the topographic complexity, the grid vertical accuracy/precision and the depth range (typically 1 m).
- MBES backscatter image at an appropriate resolution, produced by gridding the swath bathymetry backscatter data to a regular grid, as: a single or tiled set of xyz text files (*.xyz/*.pts) without overlaps together with projection information saved in a .prj file; **and** a single or tiled raster/grid without overlaps.
- Bathymetry Total Vertical Uncertainty (TVU) and Total Horizontal Uncertainty (THU) grids at an appropriate resolution, as: a single or tiled set of xyz text files (*.xyz/*.pts) without overlaps together with projection information saved in a .prj file; **and** a single or tiled raster/grid without overlaps.

- Height adjusted bathymetry grid to remove survey artefacts of overlapping and crossing survey lines. This grid shall **NOT** be used for any depth related analyses but for **surface analyses only**. (Geotiff and *NetCDF-4 classic grid data format)
- The bathymetry slope in degrees calculated from the height adjusted bathymetry grid as a single or tiled set of xyz text files (*.xyz/*.pts) without overlaps together with projection information saved in a .prj file; **and** a single or tiled raster/grid without overlaps.
- A time-stamp indexed text file of the tidal correction.
- Water column data over wrecks and other obstacles shall be supplied.
- Interpreted:
- Multi Beam Echo Sounder data series should have a Contact table and associated point, line and polygon spatial data files with columns for:
 - unique ID;
 - Contact classification (wreck, boulder, debris, etc.);
 - X co-ordinate (centre);
 - Y co-ordinate (centre);dimension(s);
 - short description;
 - where relevant, associated wreck number or cable/pipeline ID
 - where relevant, Z value in m LAT (highest point extracted from water column or bathymetry data)
 and columns as appropriate to relate the Unique Contact ID where multiple sensors have apparently detected the same feature.
- All raster deliverables for single-variable data should be supplied as single-band files with actual cell values (e.g. elevation, intensity). If provided in a non-ESRI GIS format (e.g. CAD, microstation), all processed deliverables listed above must be provided additionally in the project GIS archive.

2.4.6 *High resolution side scan sonar survey*

The objective of the Side Scan Sonar (SSS) Survey is to contribute to the model of the seabed including:

- identification and mapping of potentially mobile bedforms;
- identification and mapping of potential hazards or influences to the development of offshore wind farm infrastructure at the site;
- identification and mapping of natural and anthropogenic seabed features and objects;
- classification and mapping of seabed sediments.

The Side Scan Sonar survey should be run simultaneously with MBES acquisition.

Required elements

The SSS Survey must include:

- survey-wide continuous ($\geq 100\%$) high frequency (HF) Side Scan Sonar coverage
- mosaic produced at no greater than 0.5 x 0.5 m grid pitch

Required Specifications

The SSS survey should be carried out using simultaneous multiple channel, multiple frequency side scan sonar with at least two frequencies of ≥ 300 kHz and ≥ 600 kHz.

The line spacing should be defined to ensure that the SSS survey shall provide at least 100% coverage of the IA with frequency sufficient to resolve all objects larger than

0.5 m in their longest dimension, including sufficient overlap to obtain data at the nadir (the area between port and starboard scans, beneath the SSS instrument).

Instrument gain should be managed to allow SSS data to contribute optimally to the seabed classification operations.

Evaluation of proposals will be made with reference to the following method preferences:

The side-scan sonar tow fish should be towed at the optimum altitude for the water depth encountered. The towing altitude is normally expected to be between 8% and 15% of the selected sonar range. The slant range used should be set to yield >100% coverage of the survey area with ≥ 600 kHz data and with line spacings set to provide enough lateral overlap that the nadir of each line is covered by the range of at least one adjacent line. No blank nadir is to appear in the mosaic. Proposals that exploit instrumentation which eliminates a nadir gap without requiring overlap, while maintaining or improving object detection performance, are encouraged.

Scale ranges, depth of tow and tow speed should be determined on site to attain optimum resolution and area coverage.

Guidance

Interference in the SSS data from other equipment (e.g. seismic or magnetometer altimeter) should be minimised and should not impact on the SSS data quality and interpretability. Seabed features should be correlated with seabed samples and any other visual observations where provided by the CLIENT.

Proposals involving innovative SSS instrumentation, which meet the baseline specification, are encouraged.

Data Processing

Data shall be corrected for slant range, towfish skew, absorption of sound by seawater, geometric spreading and ship speed to produce the SSS mosaic. The bathymetry elevation data should be used for topographic corrections such that the corrections are carried out based on 3D positioning. The data should be mosaicked to 0.5 x 0.5 m or better and the final mosaic should be arranged so that the nadir of a line is layered behind the data of an adjacent line.

Interpretation

SSS Contact picking must be carried out, with interpreted contacts classified according to SSDMv2 standards. SSS contacts should be picked on scan plots and referenced to accurately positioned MBES features where possible. The inspection should target the features *at minimum*:

- Wrecks;
- Both linear and point debris ≥ 0.5 m in any dimension;
- Locations of Boulders ≥ 0.5 m in any dimension, or perimeters of boulder fields where number density is > 20 per 100x100 m area.
- Boulders or other seabed objects ≥ 1.0 m in any dimension with measured length, width and height
- Pock-marks/depressions
- Gas plumes;
- Cables;
- Pipelines; and
- Trawl scars and regions of trawl scars

Where a class of Contact feature is not detected within the IA, reporting of the search for and conclusions of the absence of such features is required.

The thresholds indicated are nominal, and a higher threshold and/or mapping of discrete areas of anomalously high Contact density may be appropriate if feature densities are high, subject to approval by the CLIENT. Proposed identification thresholds should be indicated within the CONTRACTOR's Project Documentation for approval by the CLIENT.

Deliverables

The following deliverables and their metadata are required at minimum:

Table 3: SSS deliverables						
Item ID	Measurement	Module R = Raw P = Processing I = Interpretation	Description	Resolution	Format	Load into GIS-database
b1	SSS	R	Raw XTF/JSF, nav corrected - High Frequency	n/a	.xtf/.jsf	N
b2			Raw XTF/JSF, nav corrected - Low Frequency	n/a	.xtf/.jsf	N
b3			SSS tracks (navigation - xyz) data, Survey line ID included as attribute	n/a	.gdb	Y
b4		P	SSS tracks (navigation - xyz) data, fix point included as attribute	n/a	.gdb	Y
b5			High frequency processed sidescan data, geo-referenced Mosaic tiles	0.5 m	Geotiff	Y
b6			Low frequency processed sidescan data, geo-referenced Mosaic tiles	0.5 m	Geotiff	Y
b7			Tile index	n/a	.gdb	Y
b8		I	SSS Contact list	n/a	.xlsx	N
b9			SSS Contact list [pnt]	n/a	.gdb, .shp	Y
b10			SSS Contact list [lin]	n/a	.gdb, .shp	Y
b11			SSS linear features (scars, sandwave crests etc) [lin]	n/a	.gdb, .shp	Y
b12			SSS area features (boulder fields, bedform classification, trawl scars etc) [pgn]	n/a	.gdb, .shp	Y
b13			Sidescan sonar contact report containing information and images	n/a	.docx	N
b14			Sidescan sonar contact report containing information and images	n/a	.pdf	N
b15			Sidescan sonar contact images	0.5 m	.gdb	Y

Notes on Sidescan Sonar deliverables

Raw:

- Side-Scan Sonar data in the form of raw, un-mosaiced data files (e.g. *.xtf or .jsf files)

Processed:

- SSS trackplot (fix point and line).
- Single or tiled Side-Scan Sonar mosaic at 0.5 m cell size without overlaps in raster format (e.g. *.tif).

Interpreted:

- Side-Scan Sonar data series should have a Contact table and associated point, line and polygon spatial data files with columns for:
 - unique ID;
 - Contact classification with SSDMv2 code (wreck, boulder, debris, etc.);

- X co-ordinate (centre);
 - Y co-ordinate (centre);
 - dimensions for object >1 m in any dimension;
 - short description;
 - where relevant, associated wreck number or cable/pipeline ID;
- and columns as appropriate to relate the Unique Contact ID where multiple sensors have apparently detected the same feature.
- Comprehensive Side Scan Sonar contact report containing information and waterfall images for all identified SSS Contacts in Microsoft Word and Adobe pdf formats.

2.4.7 Seabed Sampling

The objective of the seabed sediments sampling campaign is to collect grain size data to calibrate AGDS interpretation, and to inform the seabed mobility.

A field evaluation is required to be reported on a field log in an appropriate format for use in geological, chemical and biological investigations.

Samples are to be conserved and stored for onshore analysis using appropriate protocols to be proposed by CONTRACTOR and approved by CLIENT.

Required Elements

- Preliminary field analysis
- Sample conservation and storage
- Onshore analysis of sediment composition and grain size distribution
- USBL positioning

Specification

Table 4. Quantity of grab samples per IA

	Grab samples (quantity)
Nederwiek zuid	16
Nederwiek noord	20
Site-X	8
Buoy Area	None

Quantity of seabed sediment samples per IA are presented in Table 4. Grab samples shall be collected to provide ground-truth for the seabed classification data. Grab samples shall only be carried out after the geophysical acquisition within a survey area is complete. Additional samples acquired shall be priced at a rate equal or less than the rate provided in Annex [4].

The samples shall be distributed to adequately sample the anticipated distribution of seabed sediments and seabed morphology indicated by the geological desk study. A sample location plan shall be proposed by CONTRACTOR and agreed by CLIENT.

Guidance

Recovery of Samples and offshore sample handling Sampling equipment should be a van Veen grab or similar grab sampling device for sampling only the surface layer (if a box corer is used, the upper surface should be extracted). Sample logging immediately after a sample has been retrieved by a qualified CONTRACTOR's geologist, and photographed. The soil description shall follow EN ISO 14688.

Each recovered sample shall be photographed with quality, focus, colour and resolution adequate to resolve millimetre scale features. Sub-samples are to be labeled in an adequate manner and stored for onshore laboratory testing. Documentation of sampling must include the geographic position, water depth in LAT, time and date, sample identification number.

Sample volume needs to be sufficient to allow fine fraction analyses following EN ISO 17892-4.

Laboratory testing

All onshore laboratory testing shall be carried out at an approved geotechnical laboratory. Grain size distribution analyses shall follow EN ISO 17892-4. All soil testing shall be carried out, where applicable, respectively to Eurocode EN 1997-2, ISO 19901-8, or CLIENT approved equivalent.

Organic content shall be analysed by loss on ignition when samples show signs of organic material. Samples to be analysed for organic content shall be suggested by CONTRACTOR and approved by CLIENT.

All test data shall be presented in ASCII format for easy manipulation, data transfer, and integration. The CONTRACTOR is to ship all recovered samples to the onshore laboratory, and after testing package appropriately for conservation, transfer to storage facilities to be agreed with CLIENT.

The following deliverables and their metadata are required at minimum:

Table 6: Seabed Sampling deliverables						
Item ID	Measurement	Module S = samples A = Analyses	Description	Resolution	Format	Load into GIS-database
c1	Sampling	S	Conserved Sample material	n/a	n/a	N
c2		A	Sample Photographs	n/a	.jpg	N
c3			Sample locations with test results	n/a	.gdb	Y
c4			Field Report (included as section in GP field report)	n/a	.pdf	N
c5			Laboratory test results	n/a	ascii	N
c6			Laboratory test report	n/a	.pdf	N

Description of the requirements for reporting and charting is provided in section 2.6

2.4.8 *Magnetometry survey*

The objective of the Magnetometry (MAG) Survey is to contribute to the model of the seabed including:

- identification and mapping of natural and anthropogenic seabed features and objects;

The primary purpose of this survey will be the identification/confirmation of the positions of all pipelines and possibly electrical and communications cables. It is

acknowledged that a magnetometer survey along widely spaced lines will not be suitable for a comprehensive UXO survey. However sampling, coring and later geotechnical investigations may use the magnetometry data for UXO clearance in restricted area proximal to the sensor track. Therefore signal to noise performance, sensitivity and sensor altitude should be maintained at levels described below.

The magnetometer shall be deployed in the same survey pass as the MBES and SSS surveying.

Required elements

The MAG survey must include:

- Total Magnetic Intensity (TMI) at measurement altitude
- Calibrated, continuous magnetometer position and altitude

Required Specification

The preference of the client is for a transverse gradiometer to be deployed, comprising two (2) magnetometers mounted in a single frame.

The magnetometer survey line spacing should be equal to or smaller than the line spacing for the SSS and SBP survey, with minimal track offset from these sensors, to enable comparison of datasets.

Nominal altitude (h) of Magnetometer from seabed: $4 \text{ m} \geq h$

Magnetometer sensitivity: 0.01 nT/√Hz or better

Magnetometer sample rate: 10 Hz or greater

The magnetometer would preferably not be towed piggyback from the Side Scan Sonar. The preference of the CLIENT would be deployment of the Side scan Sonar from a separate tow point, using a separate tow cable.

Guidance

The magnetometer should be deployed at sufficient distance from the survey vessel to minimize magnetic interference from the vessel. This distance is normally expected to be at least three times the length of the vessel. Where the magnetometer is towed close to other equipment such as a Side-Scan Sonar towfish, a tow distance sufficient to prevent interference from the towfish and other instruments (e.g. seismic) should be ensured. The mounting of any position-tracking equipment (ultra short base line (USBL)) on magnetometer tow cables must also be such that interference is minimized. Deck cabling should be arranged to minimize noise.

The magnetometer should be towed as close to seabed as practicable during surveying to optimise sensitivity to small deviations in the Earth's magnetic fields such as those produced by thin submarine communications cables. CLIENT requires a target altitude of no greater than 4 m above seabed. Exceptions will be allowed in areas where the presence of bedforms may create risk of damage to the equipment, in which case the increased tow height should be approved by the CLIENT or CLIENT offshore representative. In all cases it is recommended that the distance between the magnetometer sensor and the seabed should not exceed 7 m

Data Processing

During processing, the CONTRACTOR is to edit the TMI data to remove obvious noise spikes and to de-trend the raw data to extract residual magnetic anomalies. The de-trending and reduction to residual magnetic anomaly procedures must be described in detail in the Final report. Positioning using USBL systems is preferred.

Magnetic signal with large scale spatial coherency may be indicative of geology, and CLIENT may request processing to recover such data in addition to the target picking data.

Residual magnetic anomaly data must not be interpolated between adjacent lines and residual magnetic anomaly data must under no circumstances be gridded; generation of an Analytic Signal Chart series is not required. Should it be required to plot the residual magnetometer data in plan-view in addition to plotting of the Contacts, ribbon plots should be used.

Interpretation

Magnetometry Contact picking must be carried out based on magnetic residual profile data. Ribbon plots may be useful for co-location of contacts with SSS and MBES Contacts.

Magnetometry Contacts must be identified and listed separately in a spreadsheet, along with a description of the anomaly type (positive/negative monopole, dipole). The recommended picking threshold is a peak-to-trough amplitude of ≥ 5 nT. A higher threshold may be appropriate if noise levels are high, subject to approval by the CLIENT.

Contacts must be classified *at minimum* into the following categories, with the appropriate SSDMv2 classification:

- Wreck-associated, correlated to local wreck registers, if available, and associated bathymetry/SSS Contacts;
- Debris-associated, correlated to associated bathymetry/SSS Contacts;
- Possible pipeline (with appropriate ID to indicate where multiple Contacts are thought to be associated with the same pipeline);
- Possible cable (with appropriate ID to indicate where multiple Contacts are thought to be associated with the same cable);
- Possible UXO;
- Undesignated.

Checks must be carried out on the magnetometry data to identify those magnetometry Contacts that are probably related to wrecks that are visible in the SSS/MBES data, and to identify additionally any magnetometry Contacts that may be indicative of buried wrecks (or potentially UXO). If possible UXO Contacts are identified, these must be indicated in the Contact table.

Deliverables

The following deliverables and their metadata are required at minimum:

Table 8: Magnetometry deliverables						
Item ID	Measurement	Module R = Raw P = Processing I = Interpretation	Description	Resolution	Format	Load into GIS-database
d1	MAG	R	Raw magnetometry	n/a	Ascii and prj	N
d2		P	Cleaned de-spiked MAG data after application of positioning QC and (USBL derived) layback correction	n/a	Ascii+prj	N

d3		MAG tracks (navigation) data including altitude, Survey line ID included as attribute [lin]	n/a	.gdb	Y
d4		MAG tracks (navigation) data, fix point included as attribute [pnt]	n/a	.gdb	Y
d5		Processed MAG data: Residual anomaly of TMI	n/a	Ascii+prj	Y
d6		Residual mag anomaly ribbon plot	1.0 m	Geotiff	Y
d7	I	MAG anomaly list	n/a	.xlsx	N
d8		MAG anomaly list [ptn]	n/a	.gdb	Y

Notes on magnetometry deliverables

Raw:

- Raw magnetometry is required as native sensor format, Ascii and .prj files.

Processed:

- Cleaned, de-spiked magnetometer data as text (x,y,z) files per line/file, after application of positioning QC and layback
- Magnetometer trackplot and altitude (fix point and line)
- Cleaned, de-spiked TMI residual data as text (x,y,z) files per line/file, including layback, detrended to residual anomaly

Interpreted:

- The Magnetometry data series should have a Contact table and associated point, line and polygon spatial data files with columns for:
 - unique ID;
 - Contact classification (wreck, boulder, debris, etc.);
 - X co-ordinate (centre);
 - Y co-ordinate (centre);
 - dimension(s);
 - short description;
 - where relevant, associated wreck number or cable/pipeline ID;
 - approximate total peak-to-trough magnitude;
 - approximate in-line anomaly width;
 - anomaly shape, e.g. negative monopole, positive monopole or dipole
 and columns as appropriate to relate the Unique Contact ID where multiple sensors have apparently detected the same feature.
- All raster deliverables for single-variable data should be supplied as single-band files with actual cell values (e.g. elevation, intensity). If provided in a non-ESRI GIS format (e.g. CAD, microstation), all processed deliverables listed above except the cleaned, de-spiked magnetometer data must be provided additionally in the project GIS archive.

2.4.9 Sub-Seabed seismic investigations - general

The objective of the 2D-High-Resolution Seismic (2D-UHRS) and Sub Bottom Profiling (SBP) Surveys is to contribute to the model of the seabed including:

- identification and mapping of static and potentially mobile bedforms such as megaripples and sand waves, including the thickness of potentially mobile sediments;
- identification and mapping of potential hazards or influences on the development of offshore wind farm infrastructure at the site e.g. faults, seabed or buried channels, shallow gas, peat, etc.;
- identification and mapping of significant stratigraphic and lithological horizons that characterise the site, the key geological units defined by the Geological Desk study and any other relevant literature or data;

- identification and mapping of subsurface structures that may represent changes in material properties relevant to the design, emplacement and operation of Offshore Wind Farm infrastructure.

2.4.10 *Ultra High Resolution Seismic and Sub Bottom Profiling survey – 2D*

The SBP survey is required for sufficiently detailed imaging of the Holocene formations including the base of the mobile sediments. The primary purpose of the SBP survey is to provide information about the top 5 m as this depth range is important for cable design and installation.

A 2D-UHRS data set will be acquired over the entire depth range of interest within the IA, to enable the detection, interpretation and mapping of all significant subsurface horizons including formation interfaces, buried channel features and other relevant indicators of geohazards

The seismic image and interpreted preliminary velocity field are required. The depth range of interest is from seabed to a depth not less than 100 m below seabed for the 2D-UHRS survey.

Required elements

- Single-channel, shallow penetration seismic surveying with a Sub-Bottom Profiler system (SBP), *i.e.* Pinger, Chirp, parametric or other system with equivalent performance. Sound Exposure Level single strike (SELss) specifications are required in the tender in order to support CLIENT's application for an environmental exemption (underwater noise).
- For 2D-UHRS: Multi-Channel Ultra High-Resolution Seismic (UHRS) surveying with a *high bandwidth* Sparker system suitable for the resolution and penetration specifications. Sound Exposure Level single strike (SELss) specifications are required in the tender in order to support CLIENT's application for an environmental exemption (underwater noise).

Required Specification

Data acquisition should be designed to optimise vertical and horizontal resolution (defined here as $\frac{1}{4}$ dominant wavelength), the signal-to-noise ratio and the recovery of coherent signal throughout the depth range of interest.

Near surface resolution within 5 m of seabed:	Inline trace spacing <1 m
	Vertical resolution: 0.2 m
	Nominal penetration: ≥ 3 m
Resolution to 40 m below sea bed:	Inline trace spacing ≤ 1.57 m
	Vertical resolution ≤ 0.5 m
	Nominal penetration: ≥ 40 m
Resolution from 40 m below sea bed to >100 m below sea bed:	Inline (stack) trace spacing ≤ 1.57 m
	Vertical resolution ≤ 1.5 m
	Nominal penetration: ≥ 100 m

Note that the specification is *outcome focussed* and required that the *delivered* (*i.e.* processed) data meet the resolution and signal penetration criteria.

The CMP fold of 2D-UHRS data is to be ≥ 24 real traces (without interpolation) and the maximum offset is to be not less than 90 m and not greater than 150 m.

Positioning of all components of the seismic instrumentation is to be accurately monitored using GPS antennae at key points, and supplemental positioning processes where applicable to improve accuracy. Depth control of seismic source and streamer is to be maintained within defined tolerances and described in method statements within the project documentation. All sub-seabed data are to be acquired on co-located lines with minimised offset between reflection point tracks. A track separation (between SBP and common mid point of the 2D-UHRS) threshold shall be set during the testing phase but shall not be greater than 15 m.

All systems generating acoustic signal must conform to the sound pressure specifications described in the environmental permit. Acoustic deterrent systems and procedures are to be implemented and shall be described in the project documentation.

Guidance

A line-plan must be submitted with the CONTRACTOR's proposal as a properly referenced shapefile with description of line spacings, bearings of the primary and secondary line directions. The vessel shall be steered so that the CMP is positioned on the intended line track.

Vessel(s) or other platforms selected for data acquisition must be established as *low noise* relative to the type of seismic data acquisition proposed, with particular reference to the seismic source power and spectral characteristics in the context of the sea-bed conditions of the IA. Demonstration via representative data should be provided.

SBP must be hull- or pole-mounted and provide effective heave and attitude compensation. An appropriate tidal correction should be applied to the SBP data. Parametric systems are preferred if CONTRACTOR can demonstrate track record of their successful use. Sufficient data processing is required to enable effective identification of the base of mobile sediments at the required resolution. Minimisation of ringing in the data is to be demonstrated during testing, and mitigation measures described in the proposal.

SBP and 2D-UHRS systems, if operated concurrently, must be arranged to minimise interference while optimising the horizontal resolution of each.

The 2D-UHRS equipment should include a streamer with group spacing of preferably 2 m or less and no more than 3.125 m to provide high horizontal resolution; an active streamer length of between 90 m and 150 m is required. Shot interval should be defined to deliver the required CMP fold and interval. A consistent, broad band seismic pulse is required and QA metrics demonstrating this should be provided.

It is required that seismic sources and hydrophone cables are deployed by personnel demonstrably experienced in their configuration, parameterisation and optimisation. Team composition and their project history, and track record will be part of the evaluation of bids.

Slant-cable or hybrid-cable proposals are acceptable if the vessel operations and data processing teams are demonstrated to have had prior successful experience of the systems proposed. Any required data processing and QA schemes must be described and demonstrated to be established in production work.

Data Processing

SBP and 2D-UHRS data require data processing to be applied to optimise quality and resolution. Full reporting is required for each type of data collected. Data processing

will be monitored for quality, and CLIENT may require opportunity to inspect data, provide input and request modification at any point prior to delivery. Data processing of UHRS data should be comprehensively tested, reported and signed off by CLIENT on up to 7 lines prior to production processing.

2D-UHRS data may have 'brute stacks' generated for use in the QA operations on-board. Brute Stacks should contain the minimum processing required to evaluate the quality of the recorded data. A suggested 'Brute stack' processing sequence should be provided in the proposal. Brute stacks form one element of the deliverables set.

The data are to be located using accurate source and receiver positions. Layback correction should be carried out such that each stacked trace has its own unique co-ordinate pair associated with its common mid-point (CMP). A description of the layback correction procedure must be included in the Field Report.

Full navigation editing must be carried out to ensure that erroneous, zero and duplicate co-ordinates have been removed and new values interpolated. Trace numbering must be sequential in increments of 1, with no duplicates. Navigation data must be included in header bytes 73-80 and 81-88 for pre-stack shot and receiver locations, and 181-188 for stacked CMP data.

2D-UHRS stack and SBP trace headers should conform to SEG Y Rev1 (2002)⁹ in structure and should contain the appropriate information, including survey metadata in the text header. Time correction for the source and receiver elevation to a single datum is required such that the SBP, and 2D-UHRS data have their seabed signal aligned in the processed final deliverables. Datum corrections should be written to the pre-stack header but *not* applied to the data.

Some, or all operations of the final, production processing sequence for SBP and UHRS data may be applied onboard or ashore (the preferred option). In either case the details of all processing undertaken must be explained and discussed in the Final Report. At minimum, the processing operations applied to each dataset must be described and parameter tests presented. An outline prediction of the 2D-UHRS 'Final stack' processing sequence should be provided in the proposal, with options presented as appropriate. The Final stack processing sequence should include at minimum:

- Positioning and Geometry assignment
- Denoise
- Signal conditioning (e.g. deconvolution, deghosting)
- Amplitude correction
- Stacking Velocity analysis at ≤ 1000 m interval
- Demultiple
- NMO correction, mute and stack
- Migration (pre or post stack)

The actual processing sequence is expected to be more complex than the list provided and may not be in the same order.

Interpreted seismic velocity is required to be delivered with appropriate QA metrics. Stacking velocity interpretation is required throughout the depth range of interest. Conversion to a coherent interval velocity model is required. Consideration must be made of the requirement for consistent velocity interpretation, within the bounds of the 2D approximation, at line intersections. Velocities are to be supplied as ASCII and SEG Y data.

The method by which depth values have been obtained from the seismic time picks, and the velocity used for converting seismic interpretation (SBP and UHRS) to depth must be described and provided as SEG-Y if appropriate.

⁹ May be downloaded from <http://www.seg.org/resources/publications/misc/technical-standards>.

Interpretation

The sub-seabed investigations are to be interpreted using a seismic workstation package. Both SBP and 2D-UHRS data are to be loaded to the same workstation project in the time domain. 2D-UHRS final interpretation is to be provided in the workstation project in the depth domain, converted using a preliminary velocity field to be defined during the project and approved by CLIENT. Interpretation of SBP and UHRS data together is encouraged. It is required that a single set of horizons is provided with no duplication between SBP and UHRS.

The definition of stratigraphic horizons to be interpreted shall be finalised by agreement between CLIENT and CONTRACTOR during the course of the project; up to four site-wide-equivalent sub-seabed horizons plus interpretation of buried channel-like features should be anticipated. Interpretation of indication of geohazards relevant to windfarm planning shall be provided.

The integrated interpretation of SBP and UHRS data is discussed in section 2.5.

2D Multi-Channel Ultra High Resolution Seismic survey deliverables.

The following deliverables and their metadata are required at minimum:

Table 9: Multi-Channel Ultra High-Resolution Seismic deliverables						
Item ID	Measurement	Module R = Raw P = Processing I = Interpretation	Description	Resolution	Format	Load into GIS-database
e1	UHRS Seismic	R	Raw navigation merged shots *	n/a	SEG-D	N
e2			Multichannel tracks (navigation) data, Survey line ID included as attribute [lin]	n/a	.gdb,	Y
e3			Multichannel tracks (navigation) data, fix point included as attribute [ptn]	n/a	.gdb,	Y
e4			EOL QC document (For every line, provided every 24h)	n/a	.pdf	N
e5		P	QC log sheet (provided every 24h and final version at EOJ)	n/a	.xlsx	N
e6			Brute stack *	n/a	SEG-Y	N
e7			Demultiple CMP gathers	n/a	SEG-D or SEG-Y	N
e8			Demultiple stack (time domain)	n/a	SEG-Y	N
e9						
e10			Final stack (with post migration processing) (time domain)	n/a	SEG-Y	N
e11			Interval velocity vs. time	n/a	SEG-Y	N
e12			RMS stacking velocity file	n/a	ascii	N
e13			2D-UHRS Navigation	n/a	ascii (P190)	N

Notes on multi-channel seismic deliverables:

Raw:

- Multi-channel raw seismic data with geometry and correct navigation applied (shot gathers) in SEG-Y or SEG-D format.

Processed:

- Trackplot for the multi-channel survey, based on stacked traces (point and line).

- Multi-channel processed seismic CDP gather data, without NMO application and with correct geometry and navigation and processing up to multiple attenuation applied, in SEG-Y or SEG-D format. In the time domain, to facilitate reprocessing and/or supplemental velocity analysis.
- Multi-channel processed stacked seismic data with correct navigation and tidal correction applied in SEG-Y format, before and after migration and after final scaling and filtering, in the time domain.

Sub-Bottom Profiler deliverables

The following deliverables and their metadata are required at minimum:

Table 10: Sub-Bottom Profiler deliverables						
Item ID	Measurement	Module R = Raw P = Processing I = Interpretation	Description	Resolution	Format	Load into GIS-database
f1	SBP	R	Raw data SBP with navigation applied	n/a	SEG-Y	N
f2		P	SBP tracks (navigation) data, Survey line ID as attribute [lin]	n/a	.gdb	Y
f3			SBP tracks (navigation) data, fix point included as attribute [ptn]	n/a	.gdb	Y
f4			Processed SBP data with navigation applied	n/a	SEG-Y	N
f5			SBP navigation	n/a	ascii (P190)	N

Notes on Sub-Bottom Profiler deliverables:

Raw:

- Raw SBP data with correct navigation applied in SEG-Y format (if applicable, heave information shall be provided separately and not applied to the raw data).

Processed:

- Trackplots for the SBP seismic survey.
- Processed SBP data where post-processing is required to deliver interpretable data at the resolution specified: interference is to be attenuated, and processes to achieve a compact wavelet with minimal ringing are to be applied

Interpretation

Interpretation of SBP data is to be implemented co-operatively with the 2D-UHRS such that a single, coherent set of horizons is delivered with the same vertical (depth and time-equivalent) datum. It is expected that SBP data are interpreted

where their penetration is sufficient to exploit a resolution advantage over the 2D-UHRS data.

Sub-seabed interpretation deliverables are described in section 2.5.6

All raster deliverables for single-variable data should be supplied as encoded single-band files with actual cell values (*e.g.* elevation, intensity), *not* as multi-band RGB images. If provided in a non-ESRI GIS format (*e.g.* CAD, microstation), all processed deliverables listed above must be provided additionally in the project GIS archive.

2.5 Integrated Interpretation

This section is only applicable for NW noord and Site-X.

Seabed and sub-seabed data acquired during the geophysical campaign are to be interpreted in order to form a coherent PGM. The purpose of this PGM is to deliver the set of products associated with the seabed itself (integrated interpretation of SSS, MBES, MAG and SBP and their derived data) and to inform the design of the anticipated Geotechnical Investigation. It is expected to be updated, incorporating the output of the Geotechnical Investigation to form an Integrated Ground Model (IGM) which is expected to develop the subsurface geological model extensively. The construction of the IGM is outside the scope of the Geophysical (and Geotechnical) Investigations.

The integration operations required of the PGM are principally the aggregation of the seabed data (MBES, SSS, MAG, SBP) to deliver a set of interpreted datasets, the aggregation of the sub-seabed data (UHRS, SBP) to deliver a sub-seabed workstation project, the integration of all suitable data elements into a GIS project, and the final reporting.

CLIENT expects to be closely involved with work during the interpretation of individual survey elements and the integration stage. A workshop to finalise the interpretation shall be held prior to the assembly of the draft reporting.

2.5.1 Seabed data integration

Overview

Contact picking must be carried out on SSS, magnetometry and MBES datasets. Targets should be reported as points, polygons and polylines. Linear Contacts of lengths on the order of the line-spacing or greater must be provided as polylines, not points.

Contacts shall be assigned a unique number and a table relating this to the identifiers of events on the individual sensor datasets is required.

Where a linear Contact is identified based on a number of point Contacts from one or more of the MBES, SSS and magnetometry data, both the point and linear Contacts must be retained in the deliverables. Linear Contacts that are associated with known cables/pipelines must be mapped and included in the deliverables. The CONTRACTOR shall investigate before commencement of the survey if further in-service and out-of-service cables and pipelines can be found in the area, based on their own information and on the Geological Desk Study and associated GIS archive.

An overview of active cables and pipelines known to CLIENT is included in Annex [6] -section VII (the provided GIS-file). CONTRACTOR shall investigate before commencement of the survey if further in-service and out-of-service cables and pipelines can be found in the area, based on own information.

Seabed material classification

Seabed classification shall be carried out based primarily on MBES backscatter/snippets (AGDS) and SSS data together with the seabed samples. A single seabed material map shall be produced.

Bedform classification

Bedform zonation, carried out according to a recognised, documented classification scheme, is required. It is suggested that nomenclature follows that used in the morphodynamical studies of other WFZ data packages of the Hollandse Kust series. The quantitative basis for the classification scheme selected must be described in the report and a table of parameters (bedform length, width, height and shape) for each selected class must be provided. At minimum, the following features shall be mapped:

- Megaripples
- Sandwaves
- Large sandwaves.
- Linear Tidal Sand Ridges.
- Anthropogenic features (*e.g.* dredging areas).

Where bedforms of different classes are co-located, this shall be indicated through the use of separate, overlapping class polygons (*i.e.* in an area where small dunes are superimposed on large dunes, the polygons for these two classes shall overlap).

The seabed slope (degrees) shall be calculated on levelled DTM, classified, and mapped.

The position of the crests of Sandwaves and Large Sandwaves shall be mapped.

2.5.2 *Outputs - Seabed*

The result of the MBES, MAG, SSS and sampling survey shall be:

- Seabed features as GIS layers and on one or more A0 charts at an appropriate scale showing both SSS Magnetic Contacts and MBES Contacts superimposed on the SSS mosaic. All pipelines/cables, both previously known and unknown, must be mapped both as linear and associated point Contacts.
- Seabed features as GIS layers and on one or more A0 charts at an appropriate scale showing both SSS and Magnetic Contacts (and MBES Contacts, if picked) superimposed on a ribbon plot of the processed magnetometer data. All pipelines/cables, both previously known and unknown, must be mapped both as linear and associated point Contacts.
- In addition to a full Contact list (within the report or as an appendix), the report must contain a summary table indicating the number of magnetometry Contacts of each classification.
- In addition to a full Contact list (within the report or as an appendix), the report must contain a summary table indicating the number of SSS Contacts of each classification.
- The report must contain a table of the wrecks identified through all methods. If any known wreck is not identified then the possible reasons for this must be discussed.
- If an object is located offset from the location recorded in the relevant database, both the recorded and as-found locations and dimensions must be indicated on charts and Contact tables.
- The report must contain a table of cables and pipelines identified through all methods. The report must contain an evaluation comparing the expected and actual location for cables and pipelines in the IA. The evaluation should include a map and a discussion in the text. If identity/location of (part of) cables and pipelines cannot be confirmed the reason for this shall be clearly specified.

2.5.3 Seabed data - Integrated Interpretive deliverables

The following interpretative deliverables and their metadata are required at minimum:

Item ID	Measurement	Module I = Interpretation	Description	Resolution	Format	Load into GIS-database
h1	Integrated MBES SSS MAG	I	Correlated Contact list for all sensors	n/a	.xlsx	N
h2			Correlated Contact file for all sensors [pnt]	n/a	.gdb	Y
h3			Isolated boulder table containing co-ordinates and size measurements	n/a	.xlsx	N
h4			Isolated boulder file containing co-ordinates and size measurements	n/a	.gdb	Y
h5			Bedform classification (polygon)	n/a	.gdb	Y
h6			Linear features (scars, sandwave crests etc) [lin]	n/a	.gdb	Y
h7			Area features (trawl scars, debris fields, boulder fields etc) [pgn]	n/a	.gdb	Y
h8			Sediment classification raster	TBC	Geotiff	Y
h9			Sediment classification [pgn]	n/a	.gdb	Y
h10			Sediment classification	n/a	CAD [dxf]	N
h11			Cable/pipeline table containing vertex co-ordinates	n/a	.xlsx	N
h12			Cable/pipeline table containing vertex co-ordinates [lin]	n/a	.gdb	Y

Notes on integrated interpretative deliverables:

- Boulder fields should describe the extent of the feature and be classified with suitable array of boulder frequency values.
- Sediment distribution/seabed classification, depending on the classification method used to be provided as: either a single or tiled set of xyz text files (*.xyz/*.pts) without overlaps and a single or tiled raster/grid without overlaps; **or** a digital vector file/drawing (ArcGIS, AutoCAD or Microstation format or similar).
- Separate table containing all vertex co-ordinates for each identified cable/pipeline, indexed by cable/pipeline ID.

2.5.4 Sub-seabed data integration

Subsurface data are to be interpreted using a workstation package at least capable of representation of all subsurface data elements in a common system. It must be capable of picking interfaces in the time and depth domain and rationalising those picks between the data elements and at line intersections to ensure consistency. The Kingdom application from IHS Markit is preferred, software version to be agreed at TKOM.

The interpretational framework shall be initiated using a subset of not less than 5 lines to be selected prior to survey data acquisition; these lines shall be acquired, processed and interpreted first, in close collaboration with CLIENT and the framework and strategy agreed with CLIENT prior to further interpretation. All 2D-UHRS and SBP data are to be interpreted.

The interpretation must include consistency/line-tie checks between the SBP and 2D-UHRS datasets within the same interpretation environment, and these checks must be described in the interpretative report.

Formation boundaries as required must be gridded and contoured. A single grid should be provided for each interface. The gridding methods and parameters used to generate interface grids from the original horizon files must be described in full. A quantitative discussion of the elevation uncertainty of all delivered interfaces must be included in the report.

Geohazard interpretations may be gridded or presented as horizon plots depending on their extent and continuity. The spatial extent of interfaces and geohazards is to be mapped and delivered within both seismic workstation and GIS deliverables.

If a significant portion of the subsurface is characterised by intense faulting, the characterisation of the faulting pattern (aggregated fault-throw and fault density) can replace the picking of each individual fault.

2.5.5 *Outputs – sub-seabed*

The output of the subsurface interpretation shall be:

- Seismic workstation project incorporating 2D UHRS and SBP data, horizon picks, grids, culture and other information used in interpretation.
- Geological cross-sections identifying all significant features and horizons (superimposed on the processed seismic data) for a representative subset of lines from each dataset on one or more A0 charts at an appropriate scale.
- Gridded elevation surface and contours (isolines) for each interface showing depth to base of formation/formation member/unit) below datum (LAT), provided electronically as ascii data and ArcGIS geodatabase elements.
- Gridded depth below seabed and depth below seabed contours of each formation/formation member/unit) provided electronically as ascii data and ArcGIS geodatabase elements.
- Mapped extents for each formation/formation member/unit) and laterally extensive geohazard (e.g. shallow gas, peat, buried channel or boulder-field), electronically as ascii data and ArcGIS geodatabase elements and as one or more A0 charts at an appropriate scale.
- Preliminary zonation of the site into zones of common geological sequence as ESRI shapefile, for input to geotechnical campaign planning.

2.5.6 *Sub-Seabed data - Integrated Interpretive deliverables*

The following interpretative deliverables are required at minimum:

Table 13: Sub-Seabed integrated interpretative deliverables						
Item ID	Measurement	Module I = Interpretation D = Database	Description	Resolution	Format	Load into GIS-database
i1	Integrated SBP UHRS	I	Horizon files for each interpreted stratigraphic or other horizon or interface, XYZ (in meters below LAT) and XYT	n/a	Ascii+prj	N
i2			Gridded elevation surface for each horizon or interface, reduced to LAT and MSL datums, XYZ	tbc	Ascii+prj	N
i3			Gridded elevation surface for each horizon or	tbc	Geotiff	Y

Table 13: Sub-Seabed integrated interpretative deliverables						
Item ID	Measurement	Module I = Interpretation D = Database	Description	Resolution	Format	Load into GIS- database
i4			interface, reduced to LAT and MSL datums, raster			
i5			Gridded elevation surface for each horizon or interface, below seabed, XYZ	tbc	Ascii+proj	N
i6			Gridded elevation surface for each horizon or interface, below seabed, raster	tbc	Geotiff	Y
i7			Elevation Contours for all gridded surfaces, reduced to LAT and MSL datums [line]	tbc	.shp, .gdb	Y
i8			Elevation Contours for all gridded surfaces, below seabed [line]	tbc	.shp, .gdb	Y
i9			Extent polygons for sub-seabed geology [polygon]	n/a	.shp .gdb	Y
i10			Sub-bottom Contacts that present a geohazard [point]	n/a	.shp .gdb	Y
i11			Sub-bottom Contacts that present a geohazard	n/a	.xlsx	N
i12			Laterally extensive geohazard (such as shallow gas or peat) [line, polygon]	n/a	.shp .gdb	Y
i13			Faults [line]	n/a	.shp .gdb	Y
i14			Area of faulting [polygon]	n/a	.shp .gdb	Y
i15			Preliminary zonation	n/a	.shp, .gdb	Y
		D	Kingdom Seismic Direct project including all SBP and 2D-UHRS data in the time domain. Interpreted horizons to be included in TWTT, and grids to be provided in depth below LAT.	n/a	.tks	N

Notes on sub-seabed integrated interpretation deliverables:

- Text (or csv) horizon files for each interpreted geological surface (including seabed and interfaces/features that were of too small extent or too sparse to be gridded) to be provided in an exchangeable format with at minimum fields for XY coordinates, survey line name, shot point/trace number, two way time and elevation relative to LAT and MSL
- Elevation surfaces for all interpreted horizons at an appropriate resolution (~0.25-1 x line spacing, to be agreed with CLIENT), reduced to datum and produced by gridding the horizon data to a regular grid, as an xyz text file (*.xyz/*.pts) **and** a raster/grid. Products to be delivered relative to both LAT and MSL datums.
- Elevation contours relative to LAT and MSL for all interpreted horizons at an appropriate depth.
- Depth below seabed information for all interpreted horizons at the same resolution as the elevation grids, as an xyz text file (*.xyz/*.pts) **and** a raster/grid.
- Depth below seabed contours at an appropriate interval.

- Sub-surface point geohazard (such as diffraction apices that may indicate the presence of boulders) table(s) and associated point spatial data with columns for X and Y co-ordinates at minimum and depth where appropriate.
- Formation/formation member/unit and laterally extensive geohazard (such as shallow gas or peat) extents as polygons in ArcGIS, AutoCAD or Microstation format or similar. Extent polygons should:
 - include and clearly indicate areas where the unit/feature is thought to be present but the base/top cannot be interpreted; and
 - exclude areas where the unit/feature is absent.
- Faulting as linear features (individual faults) and/or polygons (areas of faulting).

All raster deliverables for single-variable data should be supplied as single-band files with actual cell values (*e.g.* elevation, intensity), not as multi-band RGB images. If provided in a non-ESRI GIS format (*e.g.* CAD, microstation), all processed deliverables listed above must be provided additionally in the project GIS archive.

2.5.7 *Geographic Information Systems*

A project Geographic Information System (GIS) archive is to be delivered in a single GIS deliverables folder with metadata in accordance with requirements as specified in Annex [6] - Section VII Appendix A (GIS Metadata Requirements). Accompanying map document(s) (*.mxd), containing data as specified throughout this Scope of Work should be provided.

Data should ideally be provided in a geodatabase file, but shapefile data would be acceptable with appropriate handling of 'null' values.

The GIS data must be consistent with all other data deliverables (*e.g.* Contact feature classes in the GIS archive must contain the same attribute columns and values as in the Excel/text file Contact tables and report appendices, Kingdom-generated elevation grids and GIS elevation rasters should match, *etc.*).

Further specifications for GIS can be found in the RVO starting points and assumption document (Annex [6] - Section VII).

The GIS data archive must include *at minimum*:

Table 14: GIS deliverables						
Item ID	Measurement	Module M = Map D = Database Meta = Metadata	Description	Resolution	Format	Load into GIS- database
k1	all	M	Master Map document	n/a	.mxd	Y
k2	all	D	ArcGIS geodatabase	n/a	.gdb	Y
k3	Survey	D	Project area, wind farm and survey boundaries (polygons).	n/a	.gdb: polygon	Y
k4	Tracks	D	Vessel trackplot(s) and fix points.	n/a	.gdb: line, point	Y
k5	Tracks	D	Sensor trackplots and fix points	n/a	.gdb: line, point	Y
k6	Seabed	D	Bathymetry grid and contours.	Full	.gdb: raster, line	Y
k7	Seabed	D	TVU and TVH uncertainty grids.	Full	.gdb: raster	Y
k8	Seabed	D	MBES backscatter grids.	Full	.gdb: raster	Y
k9	Seabed	D	SSS mosaic	Full	.gdb: raster	Y
k10	Contacts	D	MBES, SSS and MAG Contacts	n/a	.gdb: point, line, polygon	Y
k11	Contacts	D	Boulders and Boulder fields	n/a	.gdb: point, polygon	
k12	Geology	D	Elevation grids and contours for all interpreted interfaces	Full	.gdb: raster	Y
k13	Geology	D	depth below seabed grids and contours for all interpreted interfaces	Full	.gdb: raster	Y
k14	Geology	D	Polygon extents for each identified geological unit, Formation and feature	n/a	.gdb: polygon	Y
k15	Geohazards	D	Point and polyline geohazards	n/a	.gdb: point, line	Y
k16	Geology	D	Seabed sediment sample locations	n/a	.gdb: point	Y
k17	Geology	D	Seabed sediment classification.	n/a	.gdb: polygon	Y
k18	Seabed	D	Bedform classification.	n/a	.gdb: polygon	Y
k19	Seabed	D	Geotiffs of waterfall images for all reported side scan sonar contacts.	n/a	.gdb: raster	Y
k20	all	Meta	Metadata to specification provided in Annex A06 s VII A	n/a	.gdb	Y

Notes on GIS deliverables:

- Sensor trackplots and fix points (transmitter/receiver midpoint where transmitter and receiver are not co-located; CDP-based for the UHRS trackplots).
- MBES, SSS and magnetometer Contacts (point, linear and polygon Contacts to be symbolised appropriately as per SSDMv2 guidelines; e.g. significant linear

Contacts should be recorded as line features and not points), including as-found cables, pipelines, wrecks *etc.*

- MBES and SSS Contacts may be combined into a single Feature Class/shapefile but magnetometer Contacts must be kept separate.
- Elevation and depth below seabed grids and contours for all interpreted interfaces (including gridded geohazards, *e.g.* top shallow gas). Grid and contour coverage must be consistent with the associated extent polygons.
- Polygon extents for each identified geological unit and Formation and all spatially-extensive geohazards (gas, significant channels, areas of faulting *etc.*). Areas where an interface or geohazard is thought to be present but is not interpretable must be differentiated from areas where it is thought to be absent.
- Point and polyline geohazards (suspected boulders, isolated peat occurrences of too small an extent to be gridded, *etc.*).
- The master map (*.mxd document) should include a layout containing at minimum a map window (with appropriate graticule), scale bar and legend. All data should be symbolised using similar schemes as per the report charts for ease of cross-referencing.
- Layers should be grouped into meaningful categories (background mapping, geohazards, seabed features, *etc.*) and layer and group names should be used that can be easily cross-referenced to the report text and charts (rather than simply using the feature class/grid names).

2.6 Quality Assurance and Quality Control

Annex [6] - section VI Quality Requirements and Administrative Instructions contains a brief description of the operational quality management requirements to be implemented during the survey work. A Quality Management Plan (QMP) is required, this section describes specific operational QA requirements in support of those described in Annex [6] - section VI section 1.2.5.

During data acquisition, MBES, SSS, MAG and sub-bottom (SBP and 2D UHRS) datasets shall be monitored continuously to ensure both coverage and quality (including resolution) are maintained. The survey *speed over ground* shall be no more than 4.5 knots, vessel speed will be subject to weather and current conditions encountered and may impact on data quality (particularly for the 2D UHRS data) so shall be monitored. Throughout the offshore survey activity, data quality checks shall be carried out on board by a qualified geophysicist including comparison of data collected on adjacent and perpendicular survey lines to ensure continuity. Any omissions, inconsistencies or other issues that may impair the quality, quantity or interpretation of the final data shall be immediately discussed with the CLIENT offshore representative and suitable actions agreed to rectify any dataset deficiencies.

Suitable field data processing shall be undertaken on board by suitably qualified and experienced geophysicist to identify any anomalous or specific field data of interest, so that further investigation can be made while the offshore work is ongoing as appropriate. Any specific data processing operations required as a result of the data acquisition configuration shall be associated with a QA operation onboard to assure that collected data are acceptable. The CONTRACTOR shall implement and perform suitable quality control procedures to ensure that data of appropriate quality are being collected. The CONTRACTOR shall ensure that the CLIENT offshore representative is sufficiently aware of any obligatory data processing operations that the CLIENT offshore representative can effectively perform QA role.

All offshore data processing is to be considered preliminary and subject to rework should it be found deficient. The onboard QA activities are specifically defined to assure that data acquired are fit-for-purpose. Any attempt at on-board *final* processing is to be secondary to the task of quality management of the acquired data.

Navigational accuracy, tidal height accuracy, frequency and method of navigation checks and positioning specifications shall be stated. Navigation checks shall be completed prior to leaving harbour. The procedures to be followed in event of navigational non-compliance shall be logged and the CLIENT offshore representative advised at the Worksite.

Accurate positioning is essential, and in the discussion of interpreted Contact locations, interface depths *etc.* in reports and other documentation the chain of positioning errors (Contact to instrument package to vessel to GPS network) must be considered in order to provide quantified uncertainty values. The derivation of these uncertainty values must be explicitly described.

During UHRS acquisition, daily data quality assessment shall be performed by generation of stacks with the minimum feasible data processing operations to enable evaluation of quality. The shot quality shall be continuously monitored. The QMP must include, prior to the start of production data acquisition, a set of criteria for acceptable quality. For example a shot may be deemed 'bad' if navigation is lost, feathering angle threshold is exceeded, streamer balancing is compromised, signal-to-noise ratio is compromised, source signature is poor/not constant, shot point distance is not constant and at required intervals or shots are missing/misfired, *etc.*

End-of-line quality assessment shall comprise of an end-of-line report summarising such pertinent QA monitors for all datasets being acquired. The content of the EOL QA

shall be suggested within the CONTRACTOR's proposal and finalised before production data acquisition begins.

The following must be agreed with the CLIENT before UHRS surveying commences:

- A Quality Assurance monitoring programme for the data acquisition.
- Acceptance criteria for completion of acquisition for a seismic line.

2.6.1 *Offshore Representation*

The CLIENT may require up to two (2) CLIENT offshore representative per vessel to witness the offshore phase of the surveys.

The CONTRACTOR is to be responsible for providing safety induction training for the CLIENT offshore representative who are to work on or visit any vessel in connection with the execution of the work.

The CONTRACTOR shall provide adequate facilities for the CLIENT offshore representative on any vessels to include a private cabin, office space, PC of sufficient power and with applications loaded suitable for QA operations, communication systems including satellite phone and appropriate internet connection and messing facilities. The CLIENT cabin needs to have an internet connection with a minimum speed of 512 kbits/sec upload / download.

CONTRACTOR shall provide Personal Protective Equipment (PPE), life jackets and any special offshore PPE for the CLIENT offshore representative for the duration of the project.

2.7 Reporting

The reporting requirements for the geophysical survey work are as follows:

2.7.1 *Daily & Weekly reporting*

The CONTRACTOR is to submit daily reports throughout the period of the fieldwork, providing full details of previous 24 hours' work and results. Further CONTRACTOR shall issue a weekly report providing insight in the progress of the WORK on a weekly basis. The minimum content of the daily and weekly reports is specified in Annex [6] - section VI of this CONTRACT.

The CONTRACTOR may be requested by the CLIENT to provide Data Quality Reports ("DQR") when appropriate. The DQR will not have to be provided on a daily basis but the CONTRACTOR must be prepared to compile and provide these reports under the supervision of the CLIENT offshore representative. Content of standardised elements of DQRs is to be established at the TKOM.

Upon request from the CLIENT, the CONTRACTOR shall provide a portion of raw or processed data by email or web transfer for the purpose of monitoring Quality Control. The CONTRACTOR shall provide the CLIENT such data within 24 hours of the request.

2.7.2 *Field report - Geophysics*

A Field Report shall be made available for the IA within three (3) weeks of demobilisation. The Field Report shall contain daily logs and summaries of the work completed, together with any preliminary results that can be provided.

The Field Report should include as a minimum:

- A statement of the purpose of the investigation and Scope of Work;
- A description of the work carried out, including:
 - Project personnel (GDPR compliant); vessels; equipment list;
 - Vessel Offset Diagrams for each vessel and, if instrument configurations were changed in the field, each instrument configuration;
 - Mobilisation, Testing and Calibration operations
 - Exact positions of all survey data and details of survey positioning control (positioning calibrations, geodetic data, etc.), with accompanying calibration records; field procedures, including methodology,
 - Acquisition methodology for each dataset.
 - Quality Control procedures and reference to specifications and standards adopted and any deviations from them for each survey type;
 - End-of-line reports.
 - Environmental observations;
 - Health & Safety records, Incident reports and safety meeting minutes.
 - Copies of daily reports,
 - Relevant signed calibration sheets

The CONTRACTOR shall provide a Draft Field Report, through ftp site or other electronic means, which shall be made final after processing of comments and approval by the CLIENT.

For all revisions a document version with track changes on and a final version are expected to be provided for ease of reviewing changes.

2.7.3 *Final report - Geophysics*

A Final Report shall be made available, incorporating interpretational reporting, for the NW zuid IA within ten (10) weeks and for the NW Noord IA thirteen (13) weeks following completion of the fieldwork. These Final Report shall include:

- A statement of the purpose of the investigation;
- A description of the work carried out, including methodology used for the processing of each dataset and the positioning data plus reference to specification and standards adopted and any deviations from them;
- Exact locations of all survey lines;
- Geophysical and geological data interpretation and conclusions drawn. This includes all results deliverables specified in Section 2.4, 2.5 and 2.5;
- Electronic copies of all raw and processed data from the survey;
- Charts at an appropriate scale on A0 of all outputs defined by CLIENT as required.

All reports and data deliverables shall be accompanied by metadata that are compliant with RVO's metadata requirements specified in Annex [6]-Section VII Appendix A.

The CONTRACTOR shall provide a Draft Final Report, which shall be made final after processing of comments and approval by the CLIENT.

For all revisions a document version with track changes on, a document review form (DRF) and a final version are expected to be provided for ease of reviewing changes.

It is anticipated that a physical meeting should be arranged after delivery of draft report and data, to facilitate the review and implementation of any corrections and changes required.

Deliverables

A complete data archive as defined in the preceding sections must be provided with each and all draft and final interpretative reports.

The following reporting and charting deliverables are required at minimum:

Table 11: Reporting and Chart deliverables						
Item ID	Measurement	Module R = Reports C = Charts	Description	Resolution	Format	Load into GIS- database
m1	Report and Charts	R	Mobilisation and Testing Report	n/a	.pdf	N
m2			Field (operations) Report	n/a	.pdf	N
m3			Seismic Processing Reports, (2D) - as appendix to Operations Report	n/a	.pdf	N
m4			Seabed Sampling Field and Laboratory reports – as appendix to Operations Report	n/a	.pdf	N
m5			Interpretation Report	n/a	.pdf	N
m6		C	Bathymetry overview chart	n/a	.pdf	N
m7			Seabed features overview chart	n/a	.pdf	N
m8			Seabed sediment classification chart (incl. sample locs)	n/a	.pdf	N
m9			Seabed contacts overview chart	n/a	.pdf	N
m10			Geohazards overview chart	n/a	.pdf	N
m11			Geological Cross Sections	n/a	.pdf	N
m12			Geological unit elevations and extents	n/a	.pdf	N
m13			Preliminary Zonation chart	n/a	.pdf	N

Notes on reporting and charting:

A table of file names against line names for all MBES, SSS, MAG and seismic data files as plain text file or spreadsheet is required. For lines associated with multiple line-part data files, each data file should have its own entry in the index table. The table should also contain the following information against each line name entry:

- Acquisition vessel;
- Acquisition date;
- Source type and ID;
- Receiver type and ID;
- Start and End fix points;
- Name of the relevant Vessel Offset Diagram;
- Indication of whether the file is a production file or has not been processed;

All raster deliverables for single-variable data should be supplied as single-band files with actual cell values (e.g. elevation, intensity), not as multi-band RGB images, with the exception of the SSS mosaic. If provided in a non-ESRI GIS format (e.g. CAD, microstation), all processed deliverables listed that can be included in a GIS archive must be provided additionally in the project GIS archive.

2.8 Delivery

Draft and Final deliveries should contain all reports, data and charts. Partial or interim deliveries are not encouraged. All Deliverables MUST be subject to rigorous QC by the CONTACTOR to ensure completeness and correctness of all components.

The Draft (1st and 2nd version) and Final Reports must each be accompanied by a complete set of data deliverables as defined in Section 0, including the project GIS archive. Data shall be provided via multiple portable hard drives (5) for all 3 reports, electronic delivery may be accepted with prior agreement of CLIENT, though agreement to delivery in this way is not guaranteed.

CONTRACTOR shall present the Final Reports in two webinars to be organised by CLIENT.